

# AN5342FBP, AN5342K

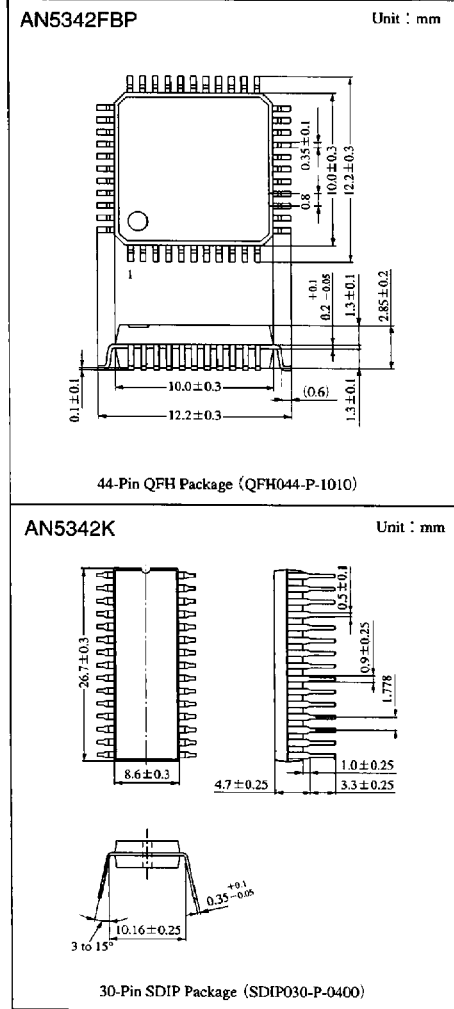
## Color TV Horizontal Aperture Correction IC

### Overview

The AN5342FBP or AN5342K is a horizontal aperture correction IC for color TV. It provides a Y signal waveform with a preshoot or overshoot feature to emphasize horizontal outlines.

### Features

- Including a circuit to add a preshoot or overshoot to a Y signal waveform
- Dynamic sharpness control
- Built-in noise reduction circuit for Y signal
- VM signal output



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### Absolute Maximum Ratings

Parameter	Symbol	Rating	Unit
Supply voltage	$V_{CC}$	11	V
Supply current	$I_{CC}$	90	mA
Power dissipation <sup>Note 2)</sup>	$P_D$	990	mW
Operating ambient temperature <sup>Note 1)</sup>	$T_{opr}$	-20 to +70	°C
Storage temperature <sup>Note 1)</sup>	$T_{stg}$	-55 to +150	°C

Note 1)  $T_a = 25^\circ\text{C}$  except operating ambient temperature and storage temperature.

Note 2) For only AN5342FBP, allowable power dissipation of the package at  $T_a = 70^\circ\text{C}$ .

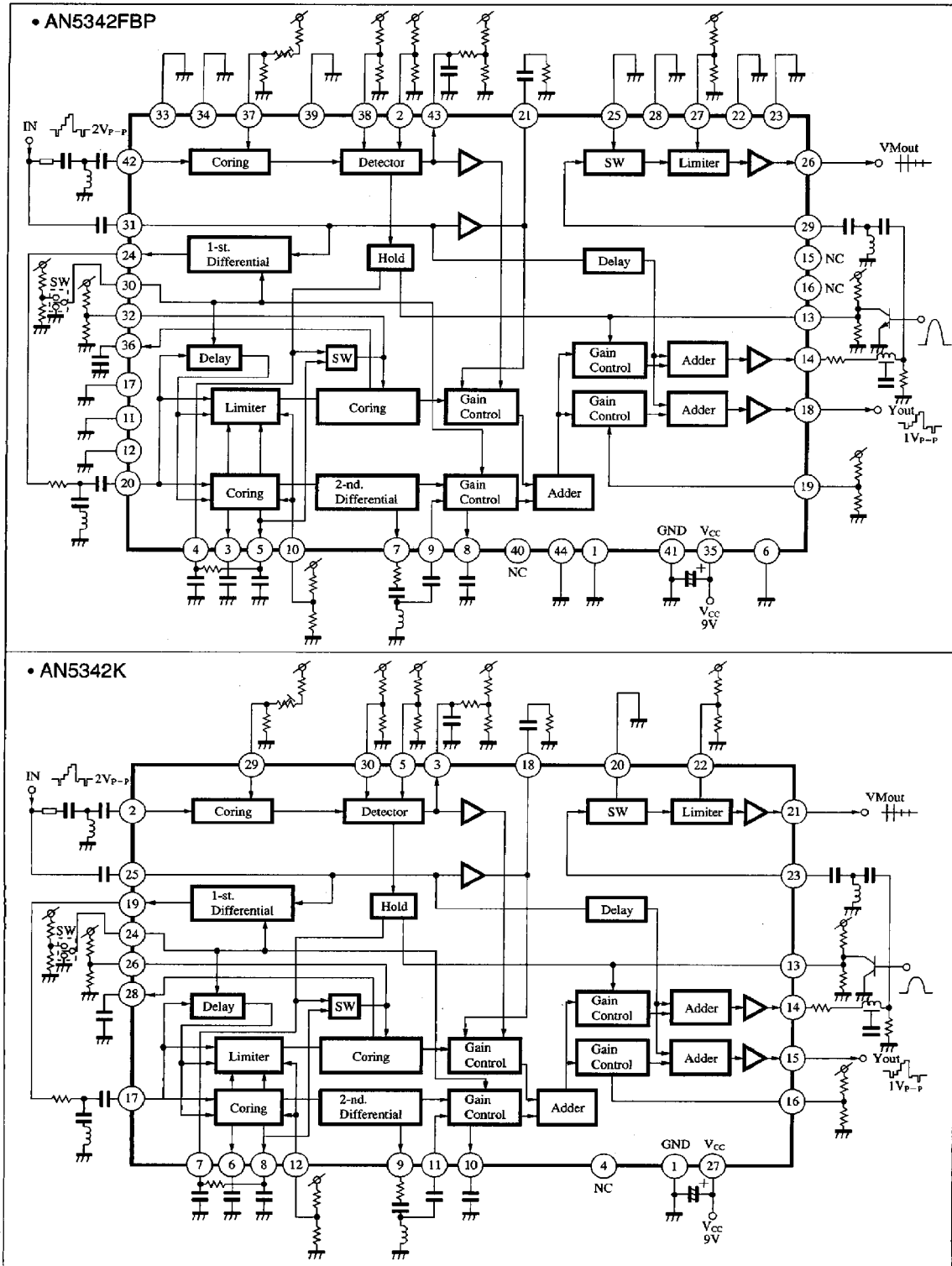
### Recommended Operating Range ( $T_a = 25^\circ\text{C}$ )

Parameter	Symbol	Range
Operating supply voltage range	$V_{CC}$	8.1V to 10.8V

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■ Block Diagram



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### ■ Pin Descriptions

#### • AN5342FBP

Pin No.	Pin name	Pin No.	Pin name
1	GND (lead frame)	23	GND (lead frame)
2	DSC large signal gain control	24	Pre-correction first differential output
3	Differential signal bias 1	25	Test Pin
4	Noise reduction bias	26	VM output
5	Differential signal bias 2	27	VM limiter control
6	GND (lead frame)	28	GND (lead frame)
7	Post-correction First Differential output	29	VM input
8	Apert. corr. Bias	30	Delay time switching
9	Second differential input	31	Y input
10	Apert. corr./detail level control	32	Detail coring control
11	GND (lead frame)	33	GND (lead frame)
12	GND (lead frame)	34	GND (lead frame)
13	VM peaking control	35	V <sub>cc</sub>
14	Y output for VM	36	Coring Bias
15	NC	37	DSC bias
16	NC	38	DSC small signal gain control
17	GND (lead frame)	39	GND (lead frame)
18	Y output	40	NC
19	Sharpness control	41	GND (main)
20	Pre-correction first differential input	42	DSC input
21	Brightness detection	43	DSC Detection output
22	GND (lead frame)	44	GND (lead frame)

#### • AN5342K

Pin No.	Pin name	Pin No.	Pin name
1	GND	16	Sharpness control
2	DSC input	17	Pre-correction first differential input
3	DSC detection output	18	Brightness Detection
4	NC	19	Pre-correction first differential output
5	DSC large signal Gain control	20	Test
6	Differential signal Bias 1	21	VM output
7	Noise reduction bias	22	VM limiter control
8	Differential signal Bias 2	23	VM input
9	Post-correction first differential output	24	Delay time switching
10	Aperture correction bias	25	Y input
11	Second differential input	26	Detail coring control
12	Aperture correction/detail separation level control	27	V <sub>cc</sub>
13	VM peaking control	28	Coring bias
14	Y output for VM	29	DSC bias
15	Y output	30	DSC small signal gain control

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**Electrical Characteristics (Ta=25±2°C) (AN5342FBP)**

Parameter	Symbol	Condition	min	typ	max	Unit
Circuit current	I <sub>35</sub>		44	55	66	mA
	I <sub>19</sub>		0.4	0.7	1.2	mA
Circuit voltage	V <sub>42-41</sub>		2.3	2.7	3.1	V
	V <sub>2-41</sub>		4.4	4.8	5.2	V
	V <sub>10-41</sub>		2.7	3.1	3.5	V
	V <sub>3-41</sub>		2.6	3.2	3.8	V
	V <sub>5-41</sub>		2.6	3.2	3.8	V
	V <sub>7-41</sub>		1.8	2.4	3.0	V
	V <sub>8-41</sub>		2.9	3.5	4.1	V
	V <sub>9-41</sub>		2.3	2.7	3.1	V
	V <sub>13-41</sub>		2.7	3.1	3.5	V
	V <sub>14-41</sub>		3.1	3.7	4.3	V
	V <sub>18-41</sub>		3.1	3.7	4.3	V
	V <sub>20-41</sub>		4.4	4.9	5.3	V
	V <sub>21-41</sub>		3.6	4.0	4.4	V
	V <sub>24-41</sub>		5.5	6.1	6.7	V
	V <sub>26-41</sub>		7.5	8.1	8.6	V
	V <sub>27-41</sub>		2.2	2.6	3.0	V
	V <sub>29-41</sub>		1.9	2.3	2.7	V
	V <sub>31-41</sub>		4.1	4.5	4.9	V
	V <sub>32-41</sub>		5.0	5.4	5.8	V
	V <sub>36-41</sub>		5.0	5.6	6.2	V
V <sub>38-41</sub>		3.9	4.3	4.7	V	
Y signal voltage gain (1)	$\Delta V_{18-41}$	$\Delta V_{18}$ at $\Delta V_{31} = 1V$	420	500	580	mV
Y signal voltage gain (2)	$\Delta V_{14-41}$	$\Delta V_{14}$ at $\Delta V_{31} = 1V$	420	500	580	mV
Y signal voltage gain (3)	$\Delta V_{21-41}$	$\Delta V_{21}$ at $\Delta V_{31} = 1V$	0.95	1.1	1.25	V
<b>Delay Section</b>						
Y signal delay time	t <sub>DL</sub> (V)	Y signal input, output delay time at DL=100ns	188	235	282	ns
Y signal frequency characteristics (1)	e <sub>r</sub> (Y <sub>1</sub> )	f=10MHz/f=1MHz at DL=100ns	-6	-4	—	dB
Y signal frequency characteristics (2)	e <sub>r</sub> (Y <sub>2</sub> )	f=10MHz/f=1MHz at DL=65ns	-6	-3	—	dB
Primary differential signal delay time	t <sub>DL</sub>	DL=100ns	80	100	120	ns
Primary differential signal delay time varying amount	$\Delta t_{DL}$	Difference at delay time change over	28	35	42	ns
<b>Aperture Correction Section</b>						
Aperture correction signal maximum gain	A <sub>v</sub> (L)	f=2MHz Output at Vin=0.5V <sub>p-p</sub>	0.7	0.9	1.3	V <sub>p-p</sub>
Aperture correction signal coring characteristics (1)	e <sub>CO</sub> (L <sub>1</sub> )	f=4MHz, Vin=75mV <sub>p-p</sub> Output amplitude at V <sub>10</sub> =1V	100	130	160	mV <sub>p-p</sub>
Aperture correction signal coring characteristics (2)	e <sub>CO</sub> (L <sub>2</sub> )	f=4MHz, Vin=75mV <sub>p-p</sub> Output amplitude at V <sub>10</sub> =5V	—	25	50	mV <sub>p-p</sub>
Aperture correction signal secondary differential gain ratio	$\Delta A_v'$ (L)	f=4Hz/f=2MHz at Vin=0.5V <sub>p-p</sub>	-6	-4	-2	dB
<b>Detail Correction Section</b>						
Detail correction signal maximum gain	A <sub>v</sub> (S)	f=4MHz Input output ratio at Vin=50mV <sub>p-p</sub>	16	18	21	dB

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■ Electrical Characteristics (cont.) (Ta = 25 ± 2°C) (AN5342FBP)

Parameter	Symbol	Condition	min	typ	max	Unit
Detail correction signal gain control (typ.)	$\Delta A_v$ (S)	f = 4MHz Vin = 50mV <sub>P-P</sub> Output ratio at V <sub>43</sub> = 5V → 3V	-8.5	-6	-3.5	dB
Detail correction signal coring characteristics	$e_{CO}$ (S)	f = 4MHz Vin = 50mV <sub>P-P</sub> Output ratio at V <sub>32</sub> = 5V → 3V	-7	-4	-2	dB
Detail correction signal limiter characteristics	$\Delta e_{LT}$ (S)	f = 4MHz Vin = 100mV <sub>P-P</sub> Output ratio at V <sub>10</sub> = 5V → 3V	—	-5	-3	dB
Detail correction signal sharpness control	$\Delta A_v'$ (S)	f = 4MHz Vin = 50mV <sub>P-P</sub> Output ratio at V <sub>19</sub> = 5V → 3V	—	-7	-4	dB

DSC Section

DSC output voltage (1)	V <sub>LIM</sub> (DSC)	f = 4MHz Output DC at Vin = 27mV <sub>P-P</sub>	2	3	4	V
DSC output voltage (2)	V <sub>S</sub> (DSC)	f = 4MHz Output DC at Vin = 150mV <sub>P-P</sub>	7.5	8.8	—	V
DSC output voltage (3)	V <sub>L</sub> (DSC)	f = 4MHz Output DC at Vin = 840mV <sub>P-P</sub>	—	0.2	1.0	V
Noise reduction characteristics	V <sub>NR</sub>	f = 4MHz Pin <sup>Ⓢ</sup> bias voltage at Vin = 150mV <sub>P-P</sub>	—	0.2	1.0	V

VM Section

VM signal maximum gain	A <sub>v</sub> (VM)	f = 4MHz Output amplitude at Vin = 100mV <sub>P-P</sub>	0.6	0.9	1.4	V <sub>P-P</sub>
VM signal limiter characteristics	$\Delta A_v$ (VM)	f = 4MHz Vin = 100mV <sub>P-P</sub> Output ratio at V <sub>27</sub> = 5V → 3V	2.5	4.0	5.5	dB
VM signal SW operation characteristics	$e_{off}$ (VM)	f = 4MHz Vin = 100mV <sub>P-P</sub> Output ratio at V <sub>25</sub> = 0 → 2V	—	-40	-25	dB
VM signal output DC level	V <sub>26-41</sub>	Difference in case between , V <sub>25</sub> = 0 and V <sub>25</sub> = 2V	-90	0	+90	mV

Reference Value

Y signal delay time variation amount	$\Delta t_{DL}$ (Y)	Delay time difference in delay time changeover	—	(35)	—	ns
Primary differential signal pulse width (1)	$\Delta t_{(DL_1)}$	Output amplitude at 125ns rise pulse inputs (DL = 100ns)	—	(190)	—	ns
Primary differential signal pulse width (2)	$\Delta t_{(DL_2)}$	Output amplitude at 125ns rise pulse inputs (DL = 65ns)	—	(225)	—	ns
Primary differential signal output amplitude (1)	A <sub>v</sub> (DL <sub>1</sub> )	Output amplitude at 125ns rise pulse inputs (DL = 100ns)	—	(0.9)	—	V <sub>P-P</sub>
Primary differential signal output amplitude (2)	A <sub>v</sub> (DL <sub>2</sub> )	Output amplitude at 125ns rise pulse inputs (DL = 65ns)	—	(0.8)	—	V <sub>P-P</sub>
Aperture correction signal gain difference at delay change-over	$\Delta A_v$ (L)	f = 2MHz, Vin = 0.5V <sub>P-P</sub> Output ratio at V <sub>30</sub> = 0 → 3V	—	(-3)	—	dB

Note) The characteristics value in parentheses is not a guaranteed value, but reference one on design.

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**Electrical Characteristics (Ta=25±2°C) (AN5342K)**

Parameter	Symbol	Condition	min	typ	max	Unit
Circuit current	I <sub>27</sub>		44	55	66	mA
	I <sub>16</sub>		0.4	0.7	1.2	mA
Circuit voltage	V <sub>2-1</sub>		2.3	2.7	3.1	V
	V <sub>5-1</sub>		4.4	4.8	5.2	V
	V <sub>12-1</sub>		2.7	3.1	3.5	V
	V <sub>6-1</sub>		2.6	3.2	3.8	V
	V <sub>8-1</sub>		2.6	3.2	3.8	V
	V <sub>9-1</sub>		1.8	2.4	3.0	V
	V <sub>10-1</sub>		2.9	3.5	4.1	V
	V <sub>11-1</sub>		2.3	2.7	3.1	V
	V <sub>13-1</sub>		2.7	3.1	3.5	V
	V <sub>14-1</sub>		3.1	3.7	4.3	V
	V <sub>15-1</sub>		3.1	3.7	4.3	V
	V <sub>17-1</sub>		4.4	4.9	5.3	V
	V <sub>18-1</sub>		3.6	4.0	4.4	V
	V <sub>19-1</sub>		5.5	6.1	6.7	V
	V <sub>21-1</sub>		7.5	8.1	8.6	V
	V <sub>22-1</sub>		2.2	2.6	3.0	V
	V <sub>23-1</sub>		1.9	2.3	2.7	V
	V <sub>25-1</sub>		4.1	4.5	4.9	V
	V <sub>26-1</sub>		5.0	5.4	5.8	V
	V <sub>28-1</sub>		5.0	5.6	6.2	V
V <sub>30-1</sub>		3.9	4.3	4.7	V	
Y signal voltage gain (1)	$\Delta V_{15-1}$	$\Delta V_{15}$ at $\Delta V_{25}=1V$	420	500	580	mV
Y signal voltage gain (2)	$\Delta V_{14-1}$	$\Delta V_{14}$ at $\Delta V_{25}=1V$	420	500	580	mV
Y signal voltage gain (3)	$\Delta V_{18-1}$	$\Delta V_{18}$ at $\Delta V_{25}=1V$	0.95	1.1	1.25	V
<b>Delay Section</b>						
Y signal delay time	t <sub>DL</sub> (Y)	Y signal input, output delay time at DL=100ns	188	235	282	ns
Y signal frequency characteristics (1)	e <sub>f</sub> (Y <sub>1</sub> )	f=10MHz/f=1MHz at DL=100ns	-6	-4	—	dB
Y signal frequency characteristics (2)	e <sub>f</sub> (Y <sub>2</sub> )	f=10MHz/f=1MHz at DL=65ns	-6	-3	—	dB
Primary differential signal delay time	t <sub>DL</sub>	DL=100ns	80	100	120	ns
Primary differential signal delay time varying amount	$\Delta t_{DL}$	Difference in delay time change-over	28	35	42	ns
<b>Aperture Correction Section</b>						
Aperture correction signal maximum gain	A <sub>v</sub> (L)	f=2MHz Output at V <sub>in</sub> =0.5V <sub>P-P</sub>	0.7	0.9	1.3	V <sub>P-P</sub>
Aperture correction signal coring characteristics (1)	e <sub>CO</sub> (L <sub>1</sub> )	f=4MHz, V <sub>in</sub> =75mV <sub>P-P</sub> Output amplitude at V <sub>12</sub> =1V	100	130	160	mV <sub>P-P</sub>
Aperture correction signal coring characteristics (2)	e <sub>CO</sub> (L <sub>2</sub> )	f=4MHz, V <sub>in</sub> =75mV <sub>P-P</sub> Output amplitude at V <sub>12</sub> =5V	—	25	50	mV <sub>P-P</sub>
Aperture correction signal secondary differential gain ratio	$\Delta A_v$ (L)	f=4MHz/f=2MHz at V <sub>in</sub> =0.5V <sub>P-P</sub>	-6	-4	-2	dB
<b>Detail Correction Section</b>						
Detail correction signal maximum gain	A <sub>v</sub> (S)	Input output ratio at V <sub>in</sub> =50mV <sub>P-P</sub>	16	18	21	dB
Detail correction signal gain control (typ.)	$\Delta A_v$ (S)	Output ratio at V <sub>3</sub> =5V→3V	-8.5	-6	-3.5	dB

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**Electrical Characteristics (cont.)** ( $T_a = 25 \pm 2^\circ\text{C}$ ) (AN5342K)

Parameter	Symbol	Condition	min	typ	max	Unit
Detail correction signal coring characteristics	$e_{CO}$ (S)	$f=4\text{MHz}$ , $V_{in}=50\text{mV}_{P-P}$ Output ratio at $V_{26}=5\text{V} \rightarrow 3\text{V}$	-7	-4	-2	dB
Detail correction signal limiter characteristics	$\Delta e_{LT}$ (S)	$f=4\text{MHz}$ , $V_{in}=100\text{mV}_{P-P}$ Output ratio at $V_{12}=5\text{V} \rightarrow 3\text{V}$	—	-5	-3	dB
Detail correction signal sharpness control	$\Delta A_V$ (S)	$f=4\text{MHz}$ , $V_{in}=50\text{mV}_{P-P}$ Output ratio at $V_{16}=5\text{V} \rightarrow 3\text{V}$	—	-7	-4	dB

## DSC Section

DSC output voltage (1)	$V_{LIM}$ (DSC)	$f=4\text{MHz}$ Output DC at $V_{in}=27\text{mV}_{P-P}$	2	3	4	V
DSC output voltage (2)	$V_S$ (DSC)	$f=4\text{MHz}$ , Output DC at $V_{in}=150\text{mV}_{P-P}$	7.5	8.8	—	V
DSC output voltage (3)	$V_L$ (DSC)	$f=4\text{MHz}$ , Output DC at $V_{in}=840\text{mV}_{P-P}$	—	0.2	1.0	V
Noise reduction characteristics	$V_{NR}$	$f=4\text{MHz}$ , $\text{Pin} \textcircled{2}$ bias voltage at $V_{in}=150\text{mV}_{P-P}$	—	0.2	1.0	V

## VM Section

VM signal maximum gain	$A_V$ (VM)	$f=4\text{MHz}$ , Output amplitude at $V_{in}=100\text{mV}_{P-P}$	0.6	0.9	1.4	$V_{P-P}$
VM signal limiter characteristics	$\Delta A_V$ (VM)	$f=4\text{MHz}$ , $V_{in}=100\text{mV}_{P-P}$ Output ratio at $V_{22}=0 \rightarrow 2\text{V}$	2.5	4.0	5.5	dB
VM signal SW operation characteristics	$e_{off}$ (VM)	$f=4\text{MHz}$ , $V_{in}=100\text{mV}_{P-P}$ Output ratio at $V_{20}=5\text{V} \rightarrow 3\text{V}$	—	-40	-25	dB
VM signal output DC level	$\Delta V_{21-1}$	$V_{CC}=9\text{V}$ , $\text{Pin} \textcircled{2}$ output voltage difference at $V_{20}=0\text{V}/2\text{V}$	-90	0	+90	mV

## Reference Value

Y signal delay time variation amount	$\Delta t_{DL}$ (Y)	Difference of delay time in delay time change-over	—	(35)	—	ns
Primary differential signal pulse width (1)	$\Delta t_{(DL_1)}$	Pulse width in 125ns pulse input (DL=100ns)	—	(190)	—	ns
Primary differential signal pulse width (2)	$\Delta t_{(DL_2)}$	Pulse width in 125ns pulse input (DL=65ns)	—	(225)	—	ns
Primary differential signal output amplitude (1)	$A_V$ (DL <sub>1</sub> )	Pulse width in 125ns pulse input (DL=100ns)	—	(0.9)	—	$V_{P-P}$
Primary differential signal output amplitude (2)	$A_V$ (DL <sub>2</sub> )	Pulse width in 125ns pulse input (DL=65ns)	—	(0.8)	—	$V_{P-P}$
Profile correction signal gain difference at delay change-over	$\Delta A_V$ (L)	$f=2\text{Mz}$ , $V_{in}=0.5\text{V}_{P-P}$ Output ratio at $V_{24}=0 \rightarrow 3\text{V}$	—	(-3)	—	dB

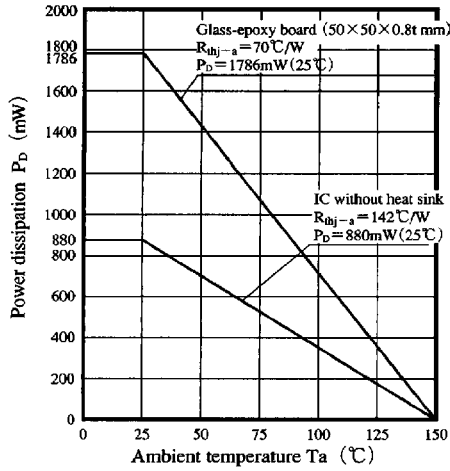
Note) The characteristics value in parentheses is not a guaranteed value, but reference one on design.

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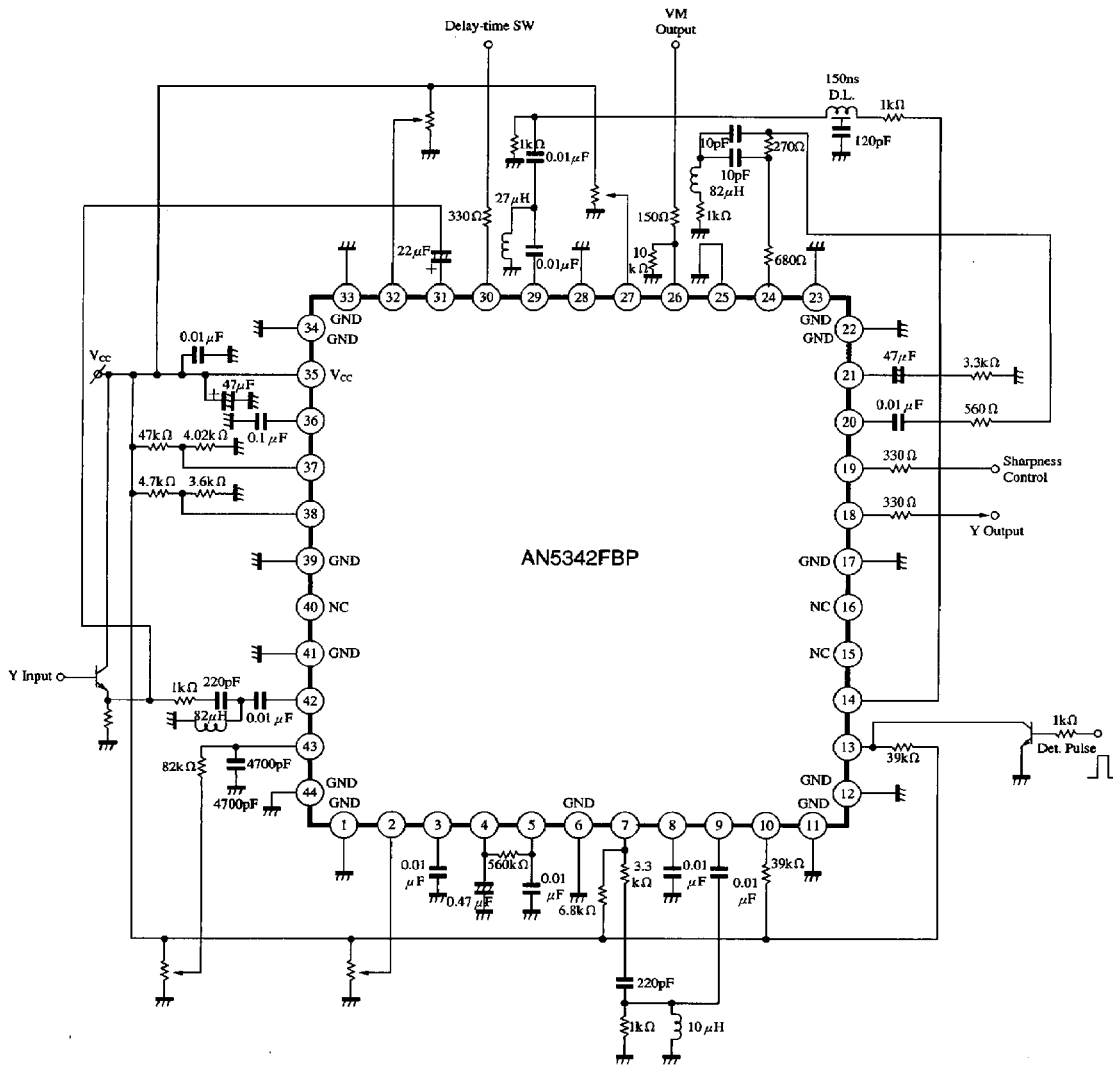
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Reference  $P_D - T_a$



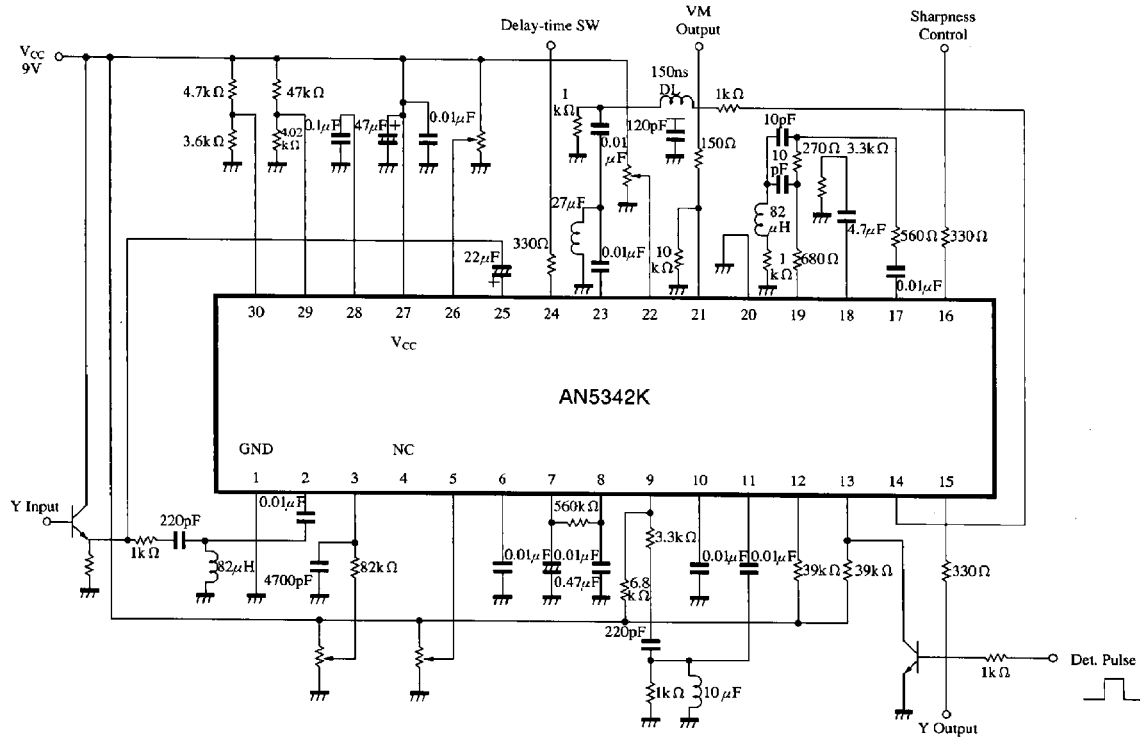
Application Circuit of AN5342FBP



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■ Application Circuit



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