

Low Distortion 750 MHz Closed-Loop Buffer Amp

AD9630*

FEATURES

Excellent Gain Accuracy: 0.99 V/V Wide Bandwidth: 750 MHz Slew Rate: 1200 V/μs Low Distortion

-65 dRc @ 20 MHz

-65 dBc @ 20 MHz -80 dBc @ 4.3 MHz Settling Time

5 ns to 0.1% 8 ns to 0.02%

Low Noise: 2/4 nV/√Hz Improved Source for CLC-110

APPLICATIONS

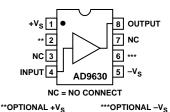
IF/Communications Impedance Transformations

Drives Flash ADCs Line Driving

GENERAL DESCRIPTION

The AD9630 is a monolithic buffer amplifier that utilizes a patented, innovative, closed-loop design technique to achieve exceptional gain accuracy, wide bandwidth, and low distortion. Slew rate limiting has been overcome as indicated by the 1200 V/µs slew rate; this improvement allows the user greater flexibility in wideband and pulse applications. The second harmonic distortion terms for an analog input tone of 4.3 MHz and 20 MHz are –80 dBc and –66 dBc, respectively. Clearly, the AD9630 establishes a new standard by combining outstanding dc and dynamic performance in one part.

PIN CONFIGURATION



NOTE: FOR BEST SETTLING TIME PERFORMANCE USE OPTIONAL POWER SUPPLIES. ALL SPECIFICATIONS ARE BASED ON USING SINGLE $\pm \rm V_S$ CONNECTIONS, EXCEPT FOR SETTLING TIME TO 0.02% AND SMALL SIGNAL S21. CONSULT THE FACTORY FOR VERSIONS WITH OPTIONAL POWER SUPPLY PINS DISCONNECTED INTERNAL TO THE PACKAGE.

The large signal bandwidth, low distortion over frequency, and drive capabilities of the AD 630 make the buffer an ideal flash ADC driver. The AD 9630 provides better signal fidelity than many of the flash ADCs that it has been designed to drive.

Other applications that require increased current frive at unity voltage gain (such as cable driving) benefit from the AD9630's performance.

The AD9630 is available in plastic DIP (N) and SOIC (R).

^{*}Protected under U.S. patent numbers 5,150,074 and 5,537,079.

AD9630-SPECIFICATIONS

ELECTRICAL CHARACTERISTICS (unless otherwise noted, $\pm V_S = \pm 5$ V; $R_{IN} = 50$ Ω , $R_{LOAD} = 100$ Ω)

			Test	AD9630AN/AR			
Parameter	Conditions	Temp	Level	Min	Typ	Max	Units
DC SPECIFICATIONS							
Output Offset Voltage		+25°C	I	-8	±3	+8	mV
Offset Voltage TC		Full	IV	-40	±8	+40	μV/°C
Input Bias Current		+25°C	I	-25	±2	+25	μΑ
Bias Current TC		Full	IV	-100	±20	+100	nA/°C
						T100	
Input Resistance		+25 to T _{MAX}	II	300	450		kΩ
		T _{MIN}	VI	150	250		kΩ
Input Capacitance		+25°C _	V		1.0		pF
Gain	$V_{OUT} = 2 V p-p$	+25 to T_{MAX}	II	0.983	0.990		V/V
	$V_{OUT} = 2 V p-p$	T_{MIN}	VI	0.980	0.985		V/V
Output Voltage Range		Full	VI	+3.2	±3.6	-3.2	V
Output Current (50 Ω Load)		+25 to T _{MAX}	II	50			mA
		T_{MIN}	VI	40			mA
Output Impedance	At DC	+25°C	V		0.6		Ω
PERR	$\Delta V = \pm 5\%$	Full	VI	44	55		dB
DC Nonlinearity	±2/V Full-Scale	+25°C	V		0.03		%
) = 2 (Yum Stare)	- 25 0	*	+	0.03		- 70
FREQUENCY DOMAIN							
Bandwidth (-3 dl/s)							
Small Signal	$V_0 \leq 0.7 \text{ yp-p}$	T _{MIN} to +25/	II r	400	750		MHz
\sim	$V_0 \ge 0.7 \text{ yp-p}$	T_{MAX}	II <i> </i>	330	550		MHz
Large Signal	V ₀ =5 V p-p \	T_{M} to $1+2/5$	V /		/ 120-	_	MHz
	$V_0 = 5 V_{p-p}$	T _{MAX}	v /		105		MHz
Output Peaking	≤200 MHz	Full	II /	\perp	0.4	<u> </u>	dB
Output Rolloff	≤200 MHz	Full _	<u> </u>		0	0.3	dB-
Group Delay	DC to 150 MHz	+25°C	_₹ / L		0.7		\int_{as}
Linear Phase Deviation	DC to 150 MHz	+25°C	$\gamma_{\rm v}$		0.7/	- /	Degrees
2nd Harmonic Distortion	2 V p-p; 4.3 MHz	Full	IV		, ,	-73	dBc
2nd Harmonic Distortion	2 V p-p; 4.5 WHz	Full	IV		$\frac{1}{260}$		dBc
		Full	II		-06 ~ -52	-5/8 L	dBc
2 1 H	2 V p-p; 50 MHz					70	
3rd Harmonic Distortion	2 V p-p; 4.3 MHz	Full	IV		-86	-79	dBc
	2 V p-p; 20 MHz	Full	IV		-75	-68	dBc
	2 V p-p; 50 MHz	T_{MIN} to +25	II		-47	-41	dBc
	2 V p-p; 50 MHz	T_{MAX}	II		-46	-40	dBc
Spectral Input Noise Voltage	10 MHz	+25°C	V		2.4		nV/\sqrt{Hz}
Integrated Output Noise	100 kHz – 200 MHz	+25°C	V		32		μV
TIME DOMAIN							
Slew Rate	$V_{OUT} = 5 \text{ V Step}$	+25°C	IV	700	1200		V/µs
Rise/Fall Time	$V_{OUT} = 1 \text{ V Step}$	+25°C	IV		1.1	1.7	ns
rase/I an I mic	$V_{OUT} = 1 \text{ V Step}$	T _{MIN} to T _{MAX}	IV		1.3	1.9	ns
			IV				
	$V_{OUT} = 5 \text{ V Step}$	+25°C			4.2	5.7	ns
0 1 1 1	$V_{OUT} = 5 \text{ V Step}$	T_{MIN} to T_{MAX}	IV		5.0	6.5	ns
Overshoot Amplitude	$V_{OUT} = 2 \text{ V Step}$	Full	IV		2	12	%
Settling Time							
To 0.1%	$V_{OUT} = 2 \text{ V Step}$	T_{MIN} to +25	IV		6	10	ns
	$V_{OUT} = 2 \text{ V Step}$	T_{MAX}	IV		7	12	ns
To 0.02% ⁴	$V_{OUT} = 2 \text{ V Step}$	T_{MIN} to +25	IV		8		ns
	$V_{OUT} = 2 \text{ V Step}$	T_{MAX}	V		12		ns
Differential Gain	4.4 MHz	+25°C	V		0.015		%
Differential Phase	4.4 MHz	+25°C	V		0.025		Degree
SUPPLY CURRENTS							<u> </u>
V_{CC} (+ I_{S})	$V_{CC} = +5 \text{ V}$	Full	II		19	26	mA
	$V_{CC} = +5 \text{ V}$ $V_{EE} = -5 \text{ V}$		II		19	26	
V_{EE} ($-I_{S}$)	v _{EE} − − J v	Full	11		19	۷۵	mA

NOTES

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 $^{^1\}mbox{Short-term}$ settling with 50 Ω source impedance.

Specifications subject to change without notice.

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Although the AD9630 features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.						

THEORY OF OPERATION

The AD9630 is a wide-bandwidth, closed-loop, unity-gain buffer that makes use of a new voltage-feedback architecture. This architecture brings together wide bandwidth and high slew rate along with exceptional dc linearity. Most previous wide-bandwidth buffers achieved their bandwidth by utilizing an open-loop topology which sacrificed both dc linearity and frequency distortion when driven into low load impedances. The design's high loop correction factor radically improves dc linearity and distortion characteristics without diminishing bandwidth. This, in combination with high slew rate, results in exceptionally low distortion over a wide frequency range.

The AD9630 is an excellent choice to drive high speed and high resolution analog-to-digital converters. Its output stage is designed to drive high speed flash converters with minimal or no series resistance. A current booster built into the output driver helps to maintain low distortion.

Parasitic or load capacitance (>7 pF) connected directly to the AD9630 output will result in frequency peaking. A small series resistor ($R_{\rm S}$) connected between the buffer output and capacitive load will negate this effect. Figure 1 shows the optimal value of $R_{\rm S}$ as a function of $C_{\rm L}$ to obtain the flattest frequency response. Figure 2 illustrates frequency response for various capacitive loads utilizing the recommended $R_{\rm S}$.

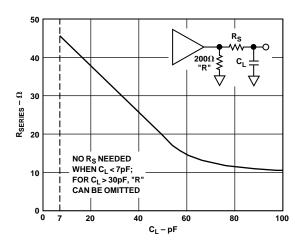
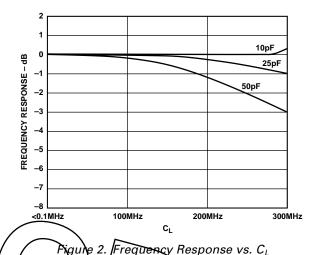


Figure 1. Recommended R_S vs. C_L

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AD9630



In pulse mode applications, with Re equal to approximately 12Ω , capacitive loads of up to 50 pF can be driven with minimal settling time degradation.)

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The output stage has short circuit protection to ground. The output driver will shut down if more than approximately 130 mA of instantaneous sink or source current is reached. This level of current ensures that output clipping will not result when driving heavy capacitive loads during high slew conditions, although average load currents above 70 mA may reduce device reliability.

LAYOUT CONSIDERATIONS

Due to the high frequency operation of the AD9630 attention to board layout is necessary to achieve optimum dynamic performance. A two ounce copper ground plane on the top side of the board is recommended; it should cover as much of the board as possible with appropriate openings for supply decoupling capacitors as well as for load and source termination resistors, (see Figure 3).

Optimum settling time and ac performance results will be achieved with surface mount $0.1~\mu F$ supply decoupling ceramic chip capacitors mounted within 50 mils of the corresponding device pins with the other side soldered directly to the ground plane. For best high resolution (<0.02%) settling times, the optional power supply pins should be decoupled as shown above. If the optional power supply pins are not used, they should be left open.

If surface mount capacitors cannot be used, radial lead ceramic capacitors with leads less than 30 mils long are recommended. Low frequency power supply decoupling is necessary and can be accomplished with 4.7 μ F tantalum capacitors mounted within 0.5 inches of the supply pins. Due to the series inductance of these capacitors interacting with the 0.1 μ F capacitors and power supply leads, high frequency oscillations might appear on

the device output. To avoid this occurrence, the power supply leads should be tightly twisted (if appropriate). Ferrite beads mounted between the tantalum and ceramic capacitors will serve the same purpose.

All unused pins (except the optional power supply pins) should be connected to ground to reduce pin-to-pin capacitive coupling and prevent external RF interference. If the source and drive electronics require "remote" operation (> 1 inch from the AD9630), the PC board line impedances should be matched with the buffer input and output resistances. Basic microstrip techniques should be observed. $R_{\rm IN}$ and $R_{\rm S}$ should be connected as close to the AD9630 as possible.

With only minimal pulse overshoot and ringing, the AD9630 can drive terminated cables directly without the use of an output termination resistor (R_S). Termination resistors (R_S and $R_{\rm IN}$) can be either standard carbon composition or microwave type. For matching characteristic impedances, precision microwave resistors of 1% or better tolerance are preferred.

The AD9630 should be soldered directly to the PC board with as little vertical clearance as possible. The use of zero insertion sockets is strongly discouraged because of the high effective pin inductances. Use of this type socket will result in peaking and

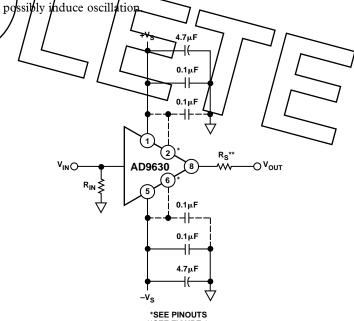
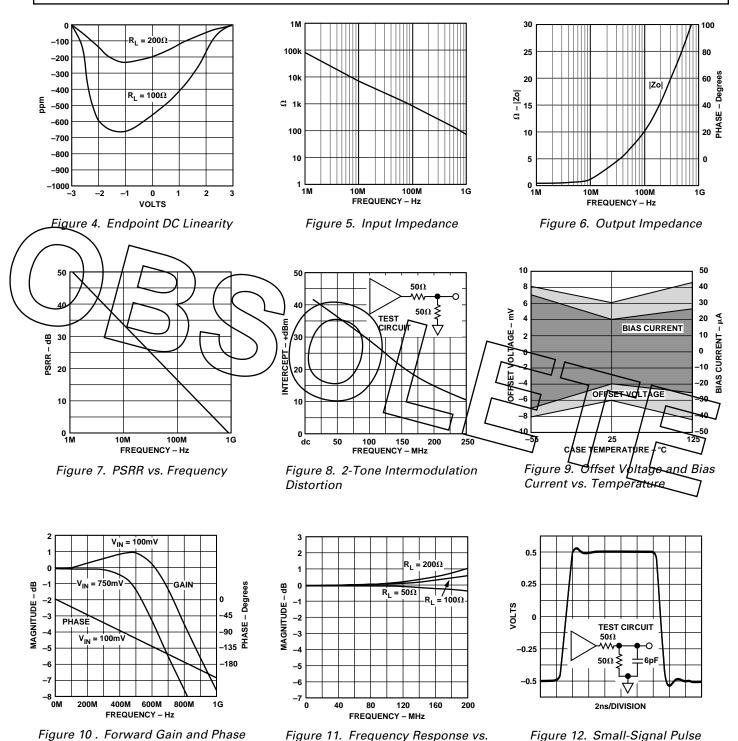


Figure 3. AD9630 Application Circuit

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Typical Performance Curves — AD9630

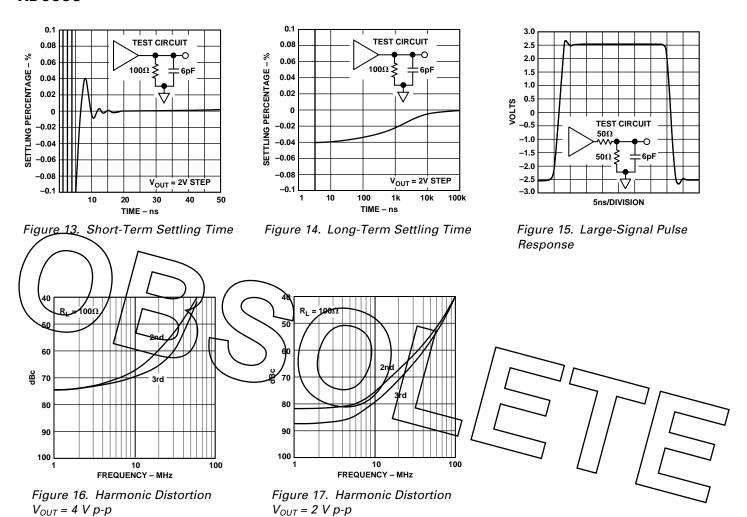
Response



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 R_{LOAD}

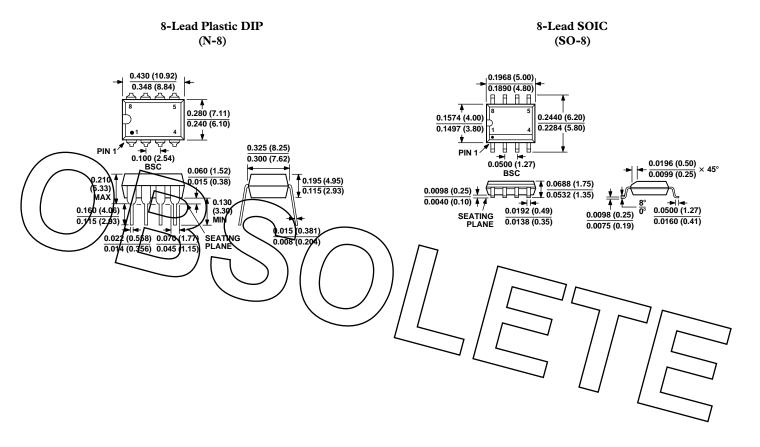
AD9630



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OUTLINE DIMENSIONS

Dimensions shown in inches and (mm).



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