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# National Semiconductor

# ADC0831/ADC0832/ADC0834/ADC0838 8-Bit Serial I/O A/D Converters with Multiplexer Options

# **General Description**

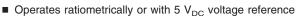
The ADC0831 series are 8-bit successive approximation A/D converters with a serial I/O and configurable input multiplexers with up to 8 channels. The serial I/O is configured to comply with the NSC MICROWIRE<sup>™</sup> serial data exchange standard for easy interface to the COPS™ family of processors, and can interface with standard shift registers or µPs.

The 2-, 4- or 8-channel multiplexers are software configured for single-ended or differential inputs as well as channel assignment.

The differential analog voltage input allows increasing the common-mode rejection and offsetting the analog zero input voltage value. In addition, the voltage reference input can be adjusted to allow encoding any smaller analog voltage span to the full 8 bits of resolution.

#### Features

- NSC MICROWIRE compatible direct interface to COPS family processors
- Easy interface to all microprocessors, or operates "stand-alone"



- No zero or full-scale adjust required
- 2-, 4- or 8-channel multiplexer options with address logic
- Shunt regulator allows operation with high voltage supplies
- OV to 5V input range with single 5V power supply
- Remote operation with serial digital data link
- TTL/MOS input/output compatible
- 0.3" standard width, 8-, 14- or 20-pin DIP package
- 20 Pin Molded Chip Carrier Package (ADC0838 only)
- Surface-Mount Package

# **Key Specifications**

#### Resolution

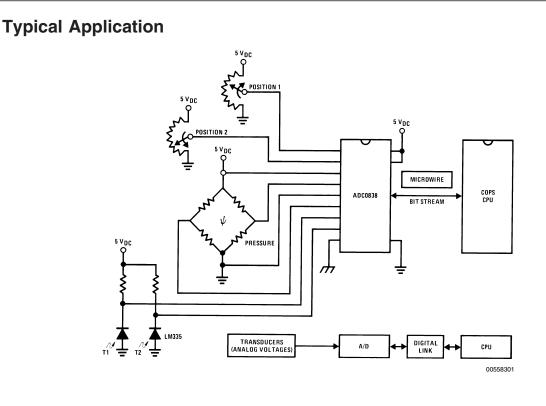
Low Power

- Total Unadjusted Error
- Single Supply
- **Conversion Time**

15 mW 32 µs

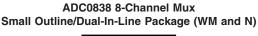
 $5 V_{DC}$ 

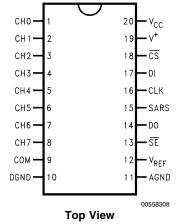
ADC0831/ADC0832/ADC0834/ADC0838 8-Bit Serial I/O A/D Converters with Multiplexer Options

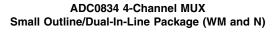


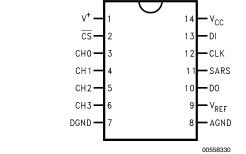
# 8 Bits $\pm \frac{1}{2}$ LSB and $\pm 1$ LSB

## **Connection Diagrams**



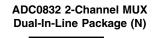


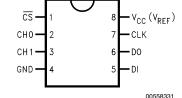




COM internally connected to A GND Top View

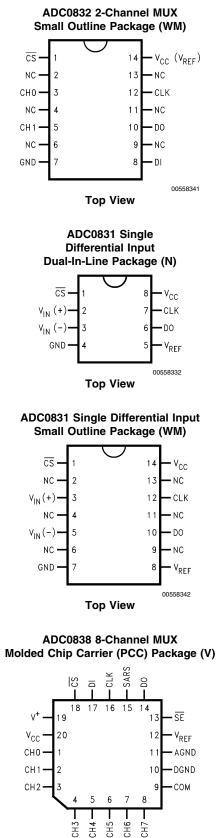
Top View





COM internally connected to GND.  $V_{\text{REF}}$  internally connected to  $V_{\text{CC}}.$  Top View

Top View



Ordering Info	ormation			
Part Number	Analog Input	Total	Package	Temperature
	Channels	Unadjusted Error		Range
ADC0831CCN	1	±1	Molded (N)	0°C to +70°C
ADC0831CCWM			SO(M)	0°C to +70°C
ADC0832CIWM	2	±1	SO(M)	–40°C to +85°C
ADC0832CCN			Molded (N)	0°C to +70°C
ADC0832CCWM			SO(M)	0°C to +70°C
ADC0834BCN	4	±1⁄2	Molded (N)	0°C to +70°C
ADC0834CCN		±1	Molded (N)	0°C to +70°C
ADC0834CCWM			SO(M)	0°C to +70°C
ADC0838BCV	8	±1⁄2	PCC (V)	0°C to +70°C
ADC0838CCV		±1	PCC (V)	0°C to +70°C
ADC0838CCN			Molded (N)	0°C to +70°C
ADC0838CIWM			SO(M)	–40°C to +85°C
ADC0838CCWM			SO(M)	0°C to +70°C

See NS Package Number M14B, M20B, N08E, N14A, N20A or V20A

# Absolute Maximum Ratings (Notes 1,

2)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

Current into V <sup>+</sup> (Note 3) Supply Voltage, V <sub>CC</sub> (Note 3)	15 mA 6.5V
Voltage	
Logic Inputs	-0.3V to V <sub>CC</sub> + 0.3V
Analog Inputs	–0.3V to V <sub>CC</sub> + 0.3V
Input Current per Pin (Note 4)	±5 mA
Package	±20 mA
Storage Temperature	–65°C to +150°C
Package Dissipation	
at T <sub>A</sub> =25°C (Board Mount)	0.8W
Lead Temperature (Soldering 10	
sec.)	

Dual-In-Line Package (Plastic)260°CMolded Chip Carrier Package215°CVapor Phase (60 sec.)215°CInfrared (15 sec.)220°CESD Susceptibility (Note 5)2000V

## Operating Ratings (Notes 1, 2)

Supply Voltage, V <sub>CC</sub>	4.5 $V_{\rm DC}$ to 6.3 $V_{\rm DC}$
Temperature Range	T <sub>MIN</sub> ≤T <sub>A</sub> ≤T <sub>MAX</sub>
ADC0832/8CIWM	–40°C to +85°C
ADC0834BCN,	
ADC0838BCV,	
ADC0831/2/4/8CCN,	
ADC0838CCV,	
ADC0831/2/4/8CCWM	0°C to +70°C

**Converter and Multiplexer Electrical Characteristics** The following specifications apply for  $V_{CC} = V_{+} = V_{REF} = 5V$ ,  $V_{REF} \le V_{CC} + 0.1V$ ,  $T_A = T_j = 25^{\circ}C$ , and  $f_{CLK} = 250$  kHz unless otherwise specified. Boldface limits apply from  $T_{MIN}$  to  $T_{MAX}$ .

		Conditions	C	IWM Device	es	-	CCV, CCWI	-	
				1	1		d CCN Dev	ices	
Parameter			Тур	Tested	Design	Тур	Tested	Design	Units
			(Note 12)	Limit	Limit	(Note 12)	Limit	Limit	
				(Note 13)	(Note 14)		(Note 13)	(Note 14)	
CONVERTER AND MULTIN	PLEXE	R CHARACTERI	STICS						
Total Unadjusted Error		$V_{REF}$ =5.00 V							
ADC0838BCV		(Note 6)					±1/2	±1⁄2	
ADC0834BCN							±1/2	±1⁄2	LSB
ADC0838CCV							±1	±1	(Max)
ADC0831/2/4/8CCN							±1	±1	
ADC0831/2/4/8CCWM							±1	±1	
ADC0832/8CIWM				±1					
Minimum Reference			3.5	1.3		3.5	1.3	1.3	kΩ
Input Resistance (Note 7)									
Maximum Reference			3.5	5.9		3.5	5.4	5.9	kΩ
Input Resistance (Note 7)									
Maximum Common-Mode				V <sub>cc</sub> +0.05			V <sub>CC</sub> +0.05	V <sub>cc</sub> +0.05	V
Input Range (Note 8)									
Minimum Common-Mode				GND -0.05			GND -0.05	GND-0.05	V
Input Range (Note 8)									
DC Common-Mode Error			±1/16	±1⁄4		±1/16	±1⁄4	±1⁄4	LSB
Change in zero		15 mA into V+							
error from $V_{CC}$ =5V		V <sub>CC</sub> =N.C.							
to internal zener		V <sub>REF</sub> =5V							
operation (Note 3)				1			1	1	LSB
V <sub>z</sub> , internal	MIN	15 mA into V+		6.3			6.3	6.3	
diode breakdown	MAX			8.5			8.5	8.5	V
(at V <sub>+</sub> ) (Note 3)									

**Converter and Multiplexer Electrical Characteristics** The following specifications apply for  $V_{CC} = V_{+} = V_{REF} = 5V$ ,  $V_{REF} \le V_{CC} + 0.1V$ ,  $T_A = T_j = 25^{\circ}C$ , and  $f_{CLK} = 250$  kHz unless otherwise specified. Boldface limits apply from  $T_{MIN}$  to  $T_{MAX}$ . (Continued)

	Conditions	c	IWM Device	es		CCV, CCWI d CCN Dev		
Parameter		Typ (Note 12)	Tested Limit (Note 13)	Design Limit (Note 14)	Typ (Note 12)	Tested Limit (Note 13)	Design Limit (Note 14)	Units
CONVERTER AND MULTIPLEX	ER CHARACTERI	STICS						
Power Supply Sensitivity	V <sub>CC</sub> =5V±5%	±1/16	±1⁄4	±1⁄4	±1/16	±1⁄4	±1⁄4	LSB
I <sub>OFF</sub> , Off Channel Leakage Current (Note 9)	On Channel=5V, Off Channel=0V		-0.2 -1			-0.2	-1	μA
	On Channel=0V, Off		+0.2			+0.2	+1	μA
	Channel=5V							
I <sub>ON</sub> , On Channel Leakage	On Channel=0V,		-0.2			-0.2	-1	μA
Current (Note 9)	Off Channel=5V		-1					
	On Channel=5V,		+0.2			+0.2	+1	μA
	Off Channel=0V		+1					
DIGITAL AND DC CHARACTER								
V <sub>IN(1)</sub> , Logical "1" Input	V <sub>cc</sub> =5.25V		2.0			2.0	2.0	V
Voltage (Min)								
V <sub>IN(0)</sub> , Logical "0" Input Voltage (Max)	V <sub>CC</sub> =4.75V		0.8			0.8	0.8	V
I <sub>IN(1)</sub> , Logical "1" Input Current (Max)	V <sub>IN</sub> =5.0V	0.005	1		0.005	1	1	μA
I <sub>IN(0)</sub> , Logical "0" Input Current (Max)	V <sub>IN</sub> =0V	-0.005	-1		-0.005	-1	-1	μA
V <sub>OUT(1)</sub> , Logical "1" Output	V <sub>CC</sub> =4.75V							
Voltage (Min)	Ι <sub>ΟUT</sub> =–360 μΑ		2.4			2.4	2.4	V
	Ι <sub>ΟUT</sub> =–10 μΑ		4.5			4.5	4.5	V
V <sub>OUT(0)</sub> , Logical "0" Output Voltage (Max)	V <sub>CC</sub> =4.75V I <sub>OUT</sub> =1.6 mA		0.4			0.4	0.4	V
I <sub>OUT</sub> , TRI-STATE Output	V <sub>OUT</sub> =0V	-0.1	-3		-0.1	-3	-3	μA
Current (Max)	V <sub>OUT</sub> =5V	0.1	3		0.1	+3	+3	μA
I <sub>SOURCE</sub> , Output Source Current (Min)	V <sub>OUT</sub> =0V	-14	-6.5		-14	-7.5	-6.5	mA
I <sub>SINK</sub> , Output Sink Current (Min)	V <sub>OUT</sub> =V <sub>CC</sub>	16	8.0		16	9.0	8.0	mA
I <sub>CC</sub> , Supply Current (Max) ADC0831, ADC0834, ADC0838		0.9	2.5		0.9	2.5	2.5	mA
ADC0832	Includes Ladder	2.3	6.5		2.3	6.5	6.5	mA
	Current							

#### AC Characteristics

The following specifications apply for  $V_{CC}$  = 5V,  $t_r$  =  $t_f$  = 20 ns and 25°C unless otherwise specified

			Тур	Tested	Design	Limit
Parameter		Conditions	(Note 12)	Limit	Limit	Units
				(Note 13)	(Note 14)	
f <sub>CLK</sub> , Clock Frequency	Min			10		kHz
	Max				400	kHz
$t_{\rm C}$ , Conversion Time		Not including MUX Addressing Time		8		1/f <sub>CLK</sub>
Clock Duty Cycle	Min				40	%
(Note 10)	Max				60	%
$t_{SET-UP}, \overline{CS}$ Falling Edge or					250	ns
Data Input Valid to CLK						
Rising Edge						
t <sub>HOLD</sub> , Data Input Valid					90	ns
after CLK Rising Edge						
t <sub>pd1</sub> , t <sub>pd0</sub> —CLK Falling		C <sub>L</sub> =100 pF				
Edge to Output Data Valid		Data MSB First	650		1500	ns
(Note 11)		Data LSB First	250		600	ns
t <sub>1H</sub> , t <sub>0H</sub> ,—Rising Edge of		C <sub>L</sub> =10 pF, R <sub>L</sub> =10k	125		250	ns
CS to Data Output and		(see TRI-STATE® Test Circuits)				
SARS Hi–Z		C <sub>L</sub> =100 pf, R <sub>L</sub> =2k		500		ns
C <sub>IN</sub> , Capacitance of Logic			5			pF
Input						
C <sub>OUT</sub> , Capacitance of Logic			5			pF
Outputs						

Note 1: Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. DC and AC electrical specifications do not apply when operating the device beyond its specified operating conditions.

Note 2: All voltages are measured with respect to the ground plugs.

**Note 3:** Internal zener diodes (6.3 to 8.5V) are connected from V+ to GND and  $V_{CC}$  to GND. The zener at V+ can operate as a shunt regulator and is connected to  $V_{CC}$  via a conventional diode. Since the zener voltage equals the A/D's breakdown voltage, the diode insures that  $V_{CC}$  will be below breakdown when the device is powered from V+. Functionality is therefore guaranteed for V+ operation even though the resultant voltage at  $V_{CC}$  may exceed the specified Absolute Max of 6.5V. It is recommended that a resistor be used to limit the max current into V+. (See *Figure 3* in Functional Description Section 6.0)

**Note 4:** When the input voltage  $(V_{IN})$  at any pin exceeds the power supply rails  $(V_{IN} < V^- \text{ or } V_{IN} > V^+)$  the absolute value of current at that pin should be limited to 5 mA or less. The 20 mA package input current limits the number of pins that can exceed the power supply boundaries with a 5 mA current limit to four.

**Note 5:** Human body model, 100 pF discharged through a 1.5 k $\Omega$  resistor.

Note 6: Total unadjusted error includes offset, full-scale, linearity, and multiplexer errors.

Note 7: Cannot be tested for ADC0832.

**Note 8:** For  $V_{IN}(-) \ge V_{IN}(+)$  the digital output code will be 0000 0000. Two on-chip diodes are tied to each analog input (see Block Diagram) which will forward conduct for analog input voltages one diode drop below ground or one diode drop greater than the  $V_{CC}$  supply. Be careful, during testing at low  $V_{CC}$  levels (4.5V), as high level analog inputs (5V) can cause this input diode to conduct — especially at elevated temperatures, and cause errors for analog inputs near full-scale. The spec allows 50 mV forward bias of either diode. This means that as long as the analog  $V_{IN}$  or  $V_{REF}$  does not exceed the supply voltage by more than 50 mV, the output code will be correct. To achieve an absolute 0  $V_{DC}$  to 5  $V_{DC}$  input voltage range will therefore require a minimum supply voltage of 4.950  $V_{DC}$  over temperature variations, initial tolerance and loading.

Note 9: Leakage current is measured with the clock not switching.

Note 10: A 40% to 60% clock duty cycle range insures proper operation at all clock frequencies. In the case that an available clock has a duty cycle outside of these limits, the minimum, time the clock is high or the minimum time the clock is low must be at least 1 µs. The maximum time the clock can be high is 60 µs. The clock can be stopped when low so long as the analog input voltage remains stable.

Note 11: Since data, MSB first, is the output of the comparator used in the successive approximation loop, an additional delay is built in (see Block Diagram) to allow for comparator response time.

Note 12: Typicals are at 25°C and represent most likely parametric norm.

Note 13: Tested limits are guaranteed to National's AOQL (Average Outgoing Quality Level).

Note 14: Guaranteed but not 100% production tested. These limits are not used to calculate outgoing quality levels.

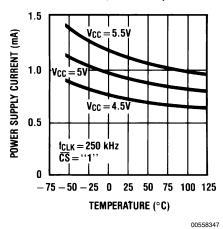


#### **Typical Performance Characteristics** Unadjusted Offset Error vs. V<sub>REF</sub> Voltage 16 $V_{IN}(+) = V_{IN}(-) = 0V + + + + +$ OFFSET ERROR (LSBs = $\frac{1}{256} \times V_{REF}$ ) 14 $V_{0S} = 2 mV$ = 25°C ∐ 12 Δ١ 10 8 6 4 2 0 0.01 0.1 1.0 5 VREF (VDC) 00558343 Linearity Error vs. Temperature 0.50 LINEARITY ERROR (LSB) 0.25 $V_{REF} = 5.0V$ fclk = 250 kHz O 150 - 100 - 50 0 50 100

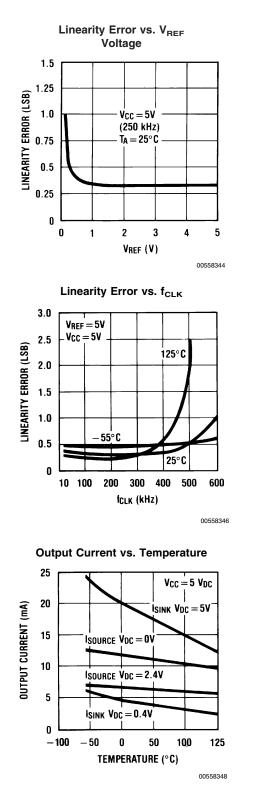
Power Supply Current vs. Temperature (ADC0838, ADC0831, ADC0834)

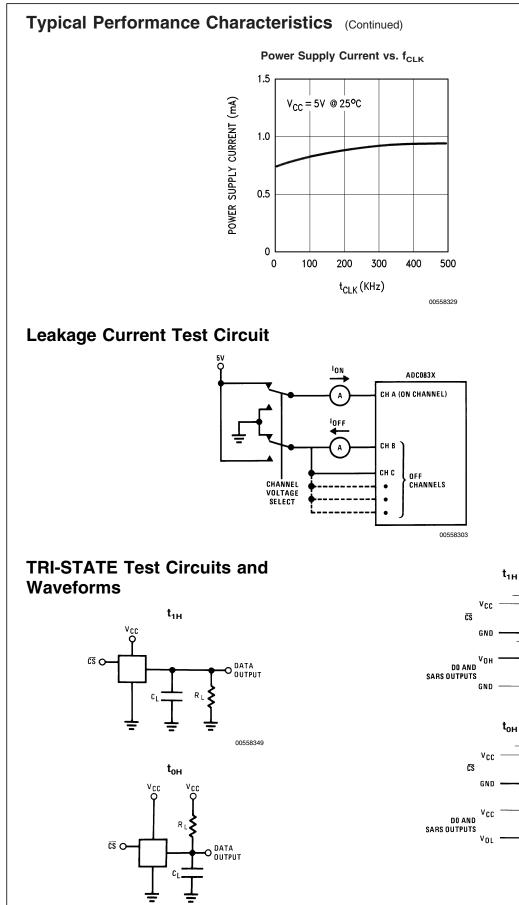
**TEMPERATURE (°C)** 

00558345



Note: For ADC0832 add IREF.





00558350

90%

90% 50%

10%

— t1H

00558351

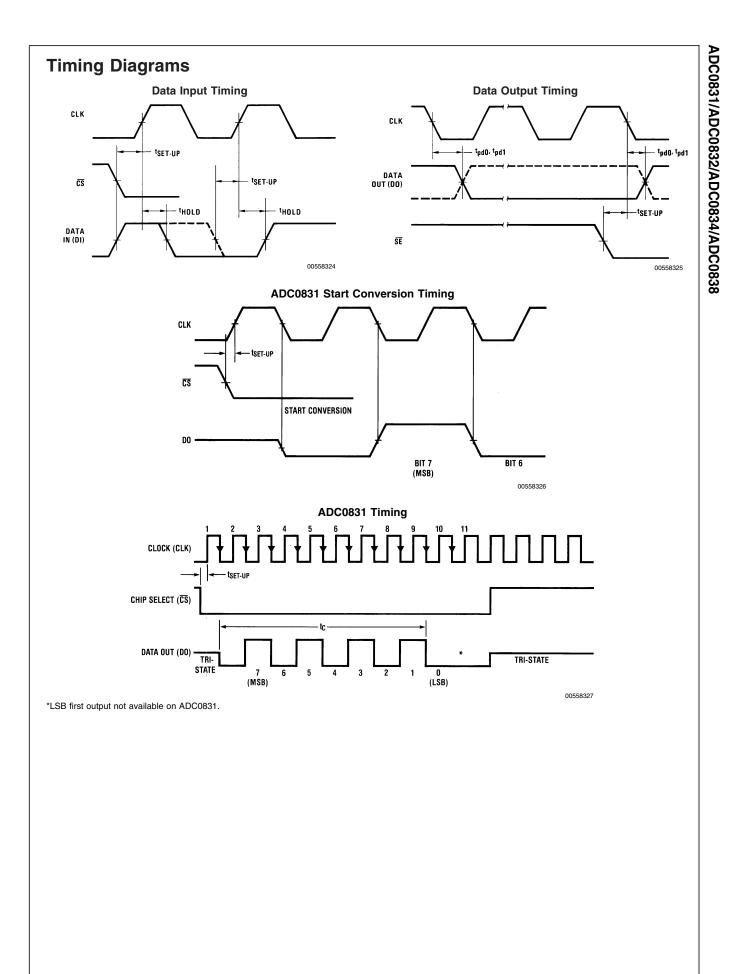
toh

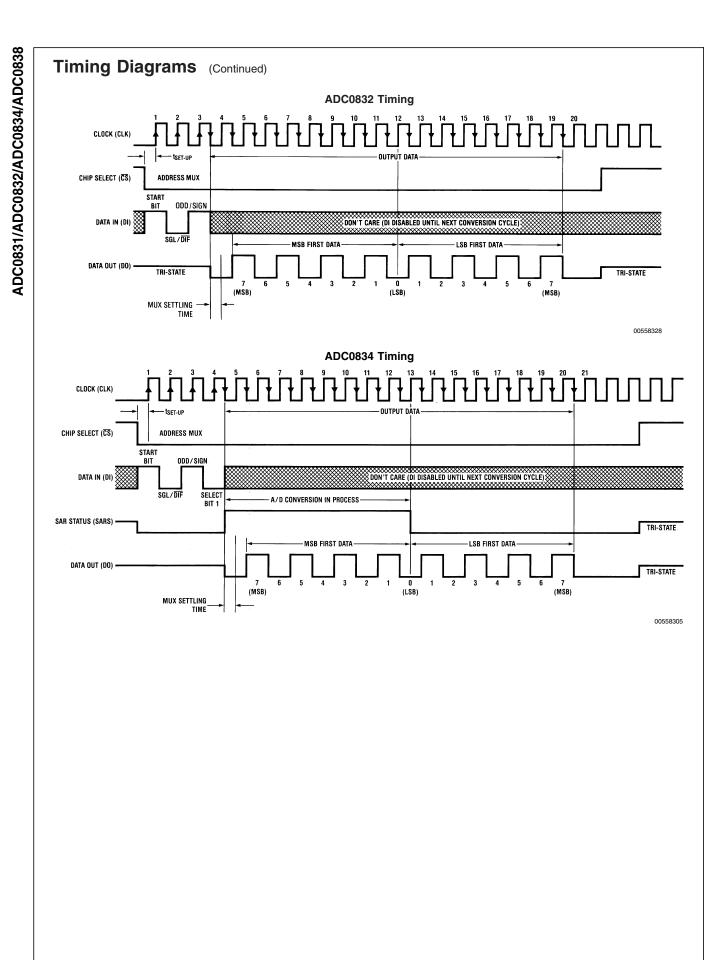
00558352

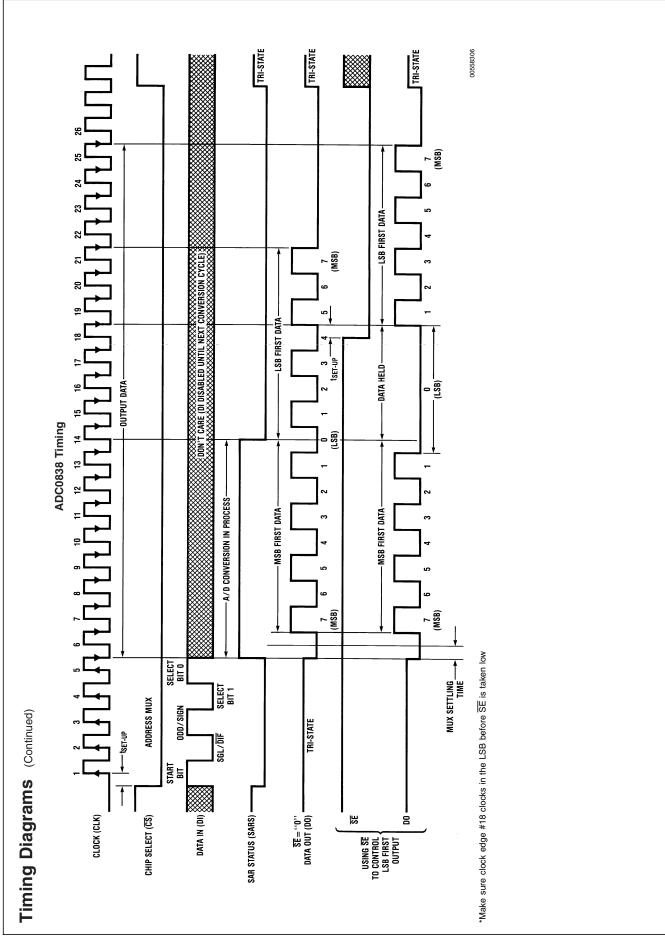
10%

nº/

50% 10%

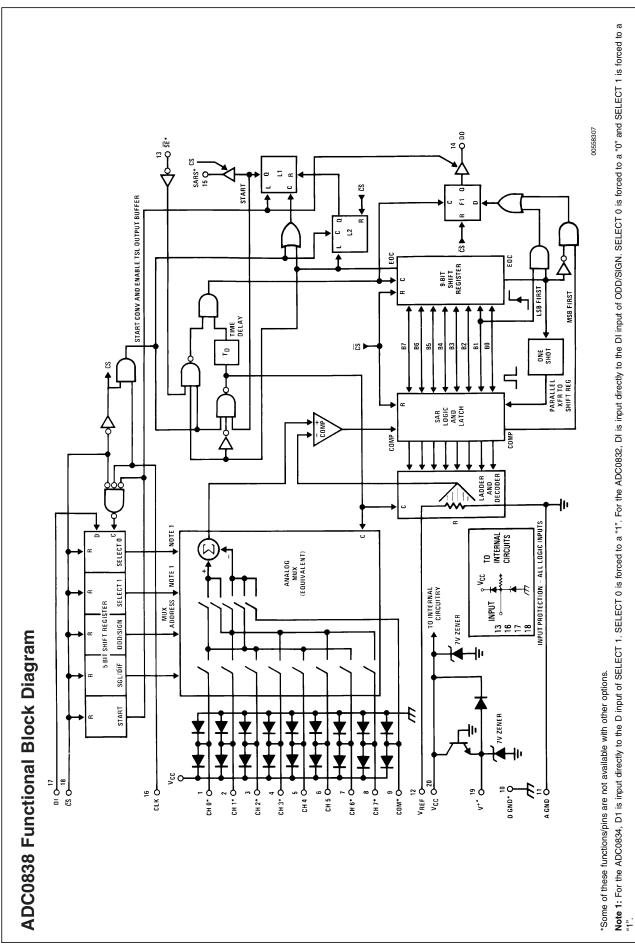






ADC0831/ADC0832/ADC0834/ADC0838

ADC0831/ADC0832/ADC0834/ADC0838



# **Functional Description**

#### 1.0 multiplexer Addressing

The design of these converters utilizes a sample-data comparator structure which provides for a differential analog input to be converted by a successive approximation routine.

The actual voltage converted is always the difference between an assigned "+" input terminal and a "-" input terminal. The polarity of each input terminal of the pair being converted indicates which line the converter expects to be the most positive. If the assigned "+" input is less than the "-" input the converter responds with an all zeros output code.

A unique input multiplexing scheme has been utilized to provide multiple analog channels with software-configurable single-ended, differential, or a new pseudo-differential option which will convert the difference between the voltage at any analog input and a common terminal. The analog signal conditioning required in transducer-based data acquisition systems is significantly simplified with this type of input flexibility. One converter package can now handle ground referenced inputs and true differential inputs as well as signals with some arbitrary reference voltage.

A particular input configuration is assigned during the MUX addressing sequence, prior to the start of a conversion. The MUX address selects which of the analog inputs are to be

enabled and whether this input is single-ended or differential. In the differential case, it also assigns the polarity of the channels. Differential inputs are restricted to adjacent channel pairs. For example channel 0 and channel 1 may be selected as a different pair but channel 0 or 1 cannot act differentially with any other channel. In addition to selecting differential mode the sign may also be selected. Channel 0 may be selected as the positive input and channel 1 as the negative input or vice versa. This programmability is best illustrated by the MUX addressing codes shown in the following tables for the various product options.

The MUX address is shifted into the converter via the DI line. Because the ADC0831 contains only one differential input channel with a fixed polarity assignment, it does not require addressing.

The common input line on the ADC0838 can be used as a pseudo-differential input. In this mode, the voltage on this pin is treated as the "–" input for any of the other input channels. This voltage does not have to be analog ground; it can be any reference potential which is common to all of the inputs. This feature is most useful in single-supply application where the analog circuitry may be biased up to a potential other than ground and the output signals are all referred to this potential.

TABLE 1. M	ultiplexer/Package	Options

Part	Number of An	Number of	
Number	Single-Ended	Differential	Package Pins
ADC0831	1	1	8
ADC0832	2	1	8
ADC0834	4	2	14
ADC0838	8	4	20

TABLE 2.	MUX Addressing:	ADC0838
----------	-----------------	---------

#### Single-Ended MUX Mode

MUX Address					Analog Single-Ended Channel #							
SGL/	ODD/	SEL	ECT	0	1	2	3	4	5	6	7	СОМ
DIF	SIGN	1	0									
1	0	0	0	+								-
1	0	0	1			+						-
1	0	1	0					+				-
1	0	1	1							+		-
1	1	0	0		+							_
1	1	0	1				+					_
1	1	1	0						+			-
1	1	1	1								+	_

#### TABLE 3. MUX Addressing: ADC0838

#### **Differential MUX Mode**

	Analog Differential Channel-Pair #										
SGL/	ODD/	SEL	ECT	(	D		1	1	2	:	3
DIF	SIGN	1	0	0	1	2	3	4	5	6	7
0	0	0	0	+	-						
0	0	0	1			+	-				
0	0	1	0					+	_		
0	0	1	1							+	_
0	1	0	0	-	+						
0	1	0	1			-	+				
0	1	1	0					-	+		
0	1	1	1							-	+

#### TABLE 4. MUX Addressing: ADC0834

#### Single-Ended MUX Mode

	MUX Addres	SS	Channel #					
SGL/	ODD/	SELECT						
DIF	SIGN	1	0	1	2	3		
1	0	0	+					
1	0	1			+			
1	1	0		+				
1	1	1				+		

COM is internally tied to A GND

#### TABLE 5. MUX Addressing: ADC0834

#### Differential MUX Mode

MUX Address			Channel #			
SGL/	ODD/	SELECT				
DIF	SIGN	1	0	1	2	3
0	0	0	+	-		
0	0	1			+	-
0	1	0	-	+		
0	1	1			-	+

#### TABLE 6. MUX Addressing: ADC0832 Single-Ended MUX Mode

MUX A	ddress	Channel #		
SGL/	ODD/	0	1	
DIF	SIGN			
1	0	+		
1	1		+	

COM is internally tied to A GND

#### TABLE 7. MUX Addressing: ADC0832 Differential MUX Mode

MUX A	ddress	Channel #		
SGL/	ODD/	0	1	
DIF	SIGN			
0	0	+	-	
0	1	-	+	

Since the input configuration is under software control, it can be modified, as required, at each conversion. A channel can be treated as a single-ended, ground referenced input for one conversion; then it can be reconfigured as part of a differential channel for another conversion. *Figure 1* illustrates the input flexibility which can be achieved.

The analog input voltages for each channel can range from 50 mV below ground to 50 mV above  $\rm V_{CC}$  (typically 5V) without degrading conversion accuracy.

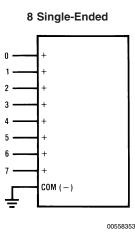
#### 2.0 THE DIGITAL INTERFACE

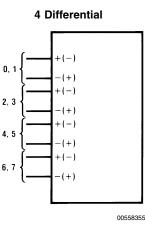
A most important characteristic of these converters is their serial data link with the controlling processor. Using a serial communication format offers two very significant system improvements; it allows more function to be included in the converter package with no increase in package size and it can eliminate the transmission of low level analog signals by locating the converter right at the analog sensor; transmitting highly noise immune digital data back to the host processor.

To understand the operation of these converters it is best to refer to the Timing Diagrams and Functional Block Diagram and to follow a complete conversion sequence. For clarity a separate diagram is shown of each device.

1. A conversion is initiated by first pulling the  $\overline{CS}$  (chip select) line low. This line must be held low for the entire conversion. The converter is now waiting for a start bit and its MUX assignment word.

2. A clock is then generated by the processor (if not provided continuously) and output to the A/D clock input.





8 Pseudo-Differential



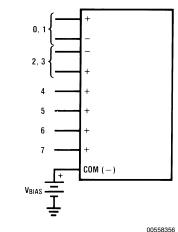


FIGURE 1. Analog Input Multiplexer Options for the ADC0838

3. On each rising edge of the clock the status of the data in (DI) line is clocked into the MUX address shift register. The start bit is the first logic "1" that appears on this line (all leading zeros are ignored). Following the start bit the converter expects the next 2 to 4 bits to be the MUX assignment word.

4. When the start bit has been shifted into the start location of the MUX register, the input channel has been assigned and a conversion is about to begin. An interval of ½ clock period (where nothing happens) is automatically inserted to allow the selected MUX channel to settle. The SAR status line goes high at this time to signal that a conversion is now in progress and the DI line is disabled (it no longer accepts data).

5. The data out (DO) line now comes out of TRI-STATE and provides a leading zero for this one clock period of MUX settling time.

6. When the conversion begins, the output of the SAR comparator, which indicates whether the analog input is greater than (high) or less than (low) each successive voltage from the internal resistor ladder, appears at the DO line

on each falling edge of the clock. This data is the result of the conversion being shifted out (with the MSB coming first) and can be read by the processor immediately.

7. After 8 clock periods the conversion is completed. The SAR status line returns low to indicate this  $1\!\!/_2$  clock cycle later.

8. If the programmer prefers, the data can be provided in an LSB first format [this makes use of the shift enable ( $\overline{SE}$ ) control line]. All 8 bits of the result are stored in an output shift register. On devices which do not include the  $\overline{SE}$  control line, the data, LSB first, is automatically shifted out the DO line, after the MSB first data stream. The DO line then goes low and stays low until  $\overline{CS}$  is returned high. On the ADC0838 the  $\overline{SE}$  line is brought out and if held high, the value of the LSB remains valid on the DO line. When  $\overline{SE}$  is forced low, the data is then clocked out LSB first. The ADC0831 is an exception in that its data is only output in MSB first format.

9. All internal registers are cleared when the  $\overline{CS}$  line is high. If another conversion is desired,  $\overline{CS}$  must make a high to low transition followed by address information.

The DI and DO lines can be tied together and controlled through a bidirectional processor I/O bit with one wire. This is

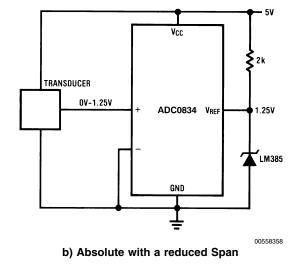
possible because the DI input is only "looked-at" during the MUX addressing interval while the DO line is still in a high impedance state.

#### 3.0 Reference Considerations

The voltage applied to the reference input to these converters defines the voltage span of the analog input (the difference between  $V_{\rm IN(MAX)}$  and  $V_{\rm IN(MIN)}$ ) over which the 256 possible output codes apply. The devices can be used in either ratiometric applications or in systems requiring absolute accuracy. The reference pin must be connected to a voltage source capable of driving the reference input resistance of typically 3.5 k $\Omega$ . This pin is the top of a resistor divider string used for the successive approximation conversion.

In a ratiometric system, the analog input voltage is proportional to the voltage used for the A/D reference. This voltage is typically the system power supply, so the  $V_{\mathsf{REF}}$  pin can be

a) Ratiometric



tied to  $V_{\rm CC}$  (done internally on the ADC0832). This technique relaxes the stability requirements of the system reference as

the analog input and A/D reference move together maintain-

For absolute accuracy, where the analog input varies between very specific voltage limits, the reference pin can be

biased with a time and temperature stable voltage source.

The LM385 and LM336 reference diodes are good low cur-

The maximum value of the reference is limited to the V<sub>CC</sub>

supply voltage. The minimum value, however, can be quite

small (see Typical Performance Characteristics) to allow

direct conversions of transducer outputs providing less than

a 5V output span. Particular care must be taken with regard

to noise pickup, circuit layout and system error voltage

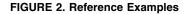
sources when operating with a reduced span due to the

increased sensitivity of the converter (1 LSB equals

ing the same output code for a given input condition.

rent devices to use with these converters.

V<sub>REF</sub>/256).



#### 4.0 The Analog Inputs

The most important feature of these converters is that they can be located right at the analog signal source and through just a few wires can communicate with a controlling processor with a highly noise immune serial bit stream. This in itself greatly minimizes circuitry to maintain analog signal accuracy which otherwise is most susceptible to noise pickup. However, a few words are in order with regard to the analog inputs should the input be noisy to begin with or possibly riding on a large common-mode voltage.

The differential input of these converters actually reduces the effects of common-mode input noise, a signal common to both selected "+" and "-" inputs for a conversion (60 Hz is most typical). The time interval between sampling the "+" input and then the "-" input is  $1/_2$  of a clock period. The change in the common-mode voltage during this short time interval can cause conversion errors. For a sinusoidal common-mode signal this error is:

$$V_{error}(max) = V_{PEAK}(2\pi f_{CM}) \left( \frac{0.5}{f_{CLK}} \right)$$

where  $\mathbf{f}_{\mathrm{CM}}$  is the frequency of the common-mode signal,

 $V_{PEAK}$  is its peak voltage value and  $f_{CLK}$ , is the A/D clock frequency.

For a 60 Hz common-mode signal to generate a  $\frac{1}{4}$  LSB error ( $\approx$ 5 mV) with the converter running at 250 kHz, its peak value would have to be 6.63V which would be larger than allowed as it exceeds the maximum analog input limits.

Due to the sampling nature of the analog inputs short spikes of current enter the "+" input and exit the "-" input at the clock edges during the actual conversion. These currents decay rapidly and do not cause errors as the internal comparator is strobed at the end of a clock period. Bypass capacitors at the inputs will average these currents and cause an effective DC current to flow through the output

resistance of the analog signal source. Bypass capacitors should not be used if the source resistance is greater than 1  $k\Omega.$ 

This source resistance limitation is important with regard to the DC leakage currents of input multiplexer as well. The worst-case leakage current of  $\pm 1 \ \mu A$  over temperature will create a 1 mV input error with a 1 k $\Omega$  source resistance. An op amp RC active low pass filter can provide both impedance buffering and noise filtering should a high impedance signal source be required.

#### 5.0 Optional Adjustments

#### 5.1 Zero Error

The zero of the A/D does not require adjustment. If the minimum analog input voltage value,  $V_{\rm IN(MIN)}$ , is not ground a zero offset can be done. The converter can be made to output 0000 0000 digital code for this minimum input voltage by biasing any  $V_{\rm IN}$  (–) input at this  $V_{\rm IN(MIN)}$  value. This utilizes the differential mode operation of the A/D.

The zero error of the A/D converter relates to the location of the first riser of the transfer function and can be measured by grounding the V<sub>IN</sub>(–) input and applying a small magnitude positive voltage to the V<sub>IN</sub>(+) input. Zero error is the difference between the actual DC input voltage which is necessary to just cause an output digital code transition from 0000 0000 to 0000 0001 and the ideal ½ LSB value (½ LSB=9.8 mV for V<sub>BEF</sub>=5.000 V<sub>DC</sub>).

#### 5.2 Full-Scale

The full-scale adjustment can be made by applying a differential input voltage which is 1  $^{1\!/_2}$  LSB down from the desired analog full-scale voltage range and then adjusting the magnitude of the  $V_{\mathsf{REF}}$  input (or  $V_{\mathsf{CC}}$  for the ADC0832) for a digital output code which is just changing from 1111 1110 to 1111 1111.

# 5.3 Adjusting for an Arbitrary Analog Input Voltage Range

If the analog zero voltage of the A/D is shifted away from ground (for example, to accommodate an analog input signal which does not go to ground), this new zero reference should be properly adjusted first. A V<sub>IN</sub> (+) voltage which equals this desired zero reference plus 1/2 LSB (where the LSB is calculated for the desired analog span, using 1 LSB= analog span/256) is applied to selected "+" input and the zero reference voltage at the corresponding "-" input should then be adjusted to just obtain the  $00_{\text{HEX}}$  to  $01_{\text{HEX}}$  code transition.

The full-scale adjustment should be made [with the proper  $V_{\rm IN}(-)$  voltage applied] by forcing a voltage to the  $V_{\rm IN}(+)$  input which is given by:

$$V_{IN}$$
 (+) fs adj =  $V_{MAX}$ -1.5  $\left[\frac{(V_{MAX} - V_{MIN})}{256}\right]$ 

where:

and

 $V_{MAX}$  = the high end of the analog input range

 $V_{MIN}$  = the low end (the offset zero) of the analog range.

(Both are ground referenced.)

The  $V_{\text{REF}}$  (or  $V_{\text{CC}})$  voltage is then adjusted to provide a code change from FE\_{\text{HEX}} to FF\_{HEX}. This completes the adjustment procedure.

#### 6.0 Power Supply

A unique feature of the ADC0838 and ADC0834 is the inclusion of a zener diode connected from the V<sup>+</sup> terminal to ground which also connects to the V<sub>CC</sub> terminal (which is the actual converter supply) through a silicon diode, as shown in *Figure 3*. (Note 3)

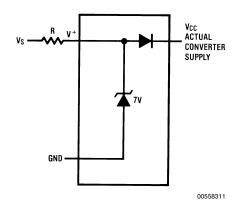


FIGURE 3. An On-Chip Shunt Regulator Diode

This zener is intended for use as a shunt voltage regulator to eliminate the need for any additional regulating components. This is most desirable if the converter is to be remotely located from the system power source. *Figure 4* and *Figure 5* illustrate two useful applications of this on-board zener when an external transistor can be afforded.

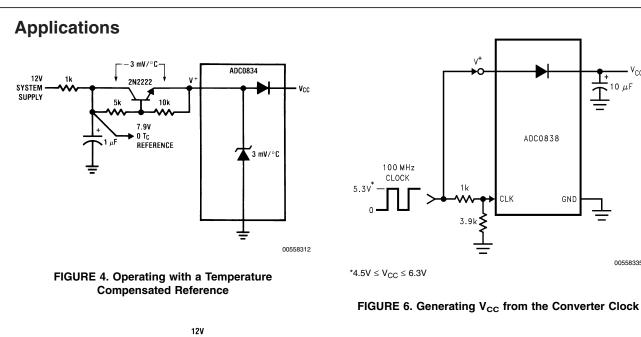
An important use of the interconnecting diode between V<sup>+</sup> and V<sub>CC</sub> is shown in *Figure 6* and *Figure 7*. Here, this diode is used as a rectifier to allow the V<sub>CC</sub> supply for the converter to be derived from the clock. The low current requirements of the A/D and the relatively high clock frequencies used (typically in the range of 10k–400 kHz) allows using the small value filter capacitor shown to keep the ripple on the V<sub>CC</sub> line to well under 1/4 of an LSB. The shunt zener regulator can also be used in this mode. This requires a clock voltage swing which is in excess of V<sub>Z</sub>. A current limit for the zener is needed, either built into the clock generator or a resistor can be used from the CLK pin to the V<sup>+</sup> pin.

V<sub>CC</sub>

00558335

<u></u><sup>10 μF</sup>

GND



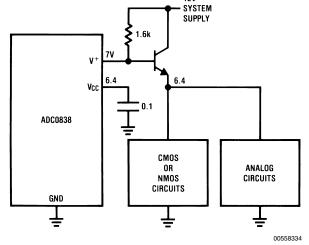


FIGURE 5. Using the A/D as the System Supply Regulator

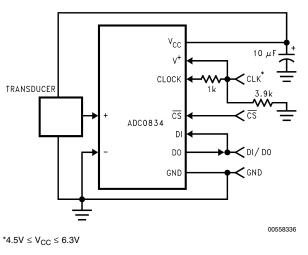
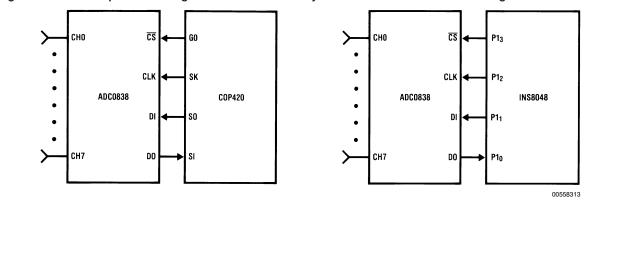
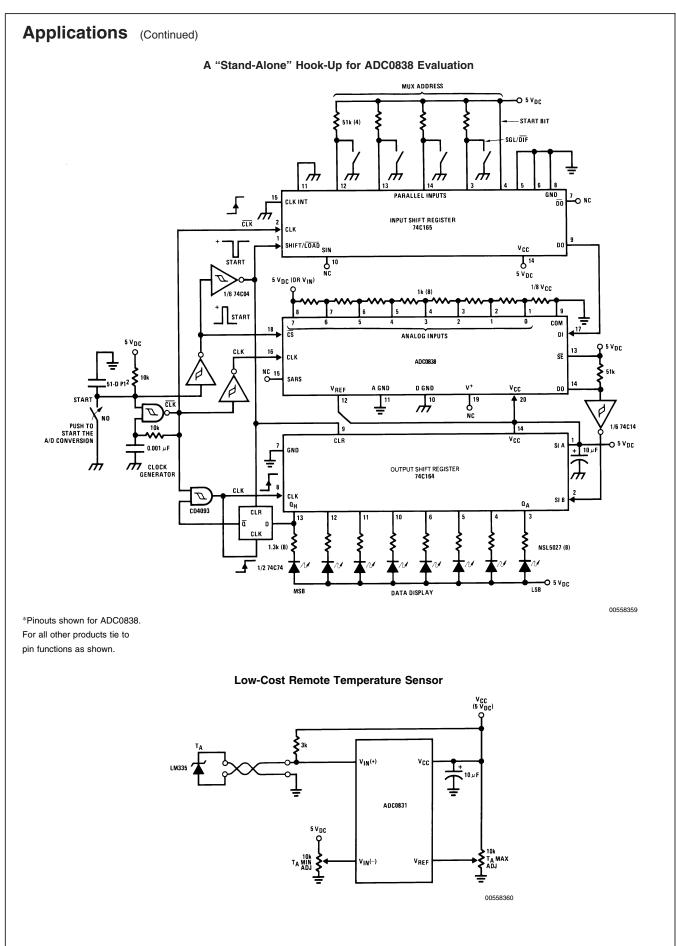


FIGURE 7. Remote Sensing -Clock and Power on 1 Wire

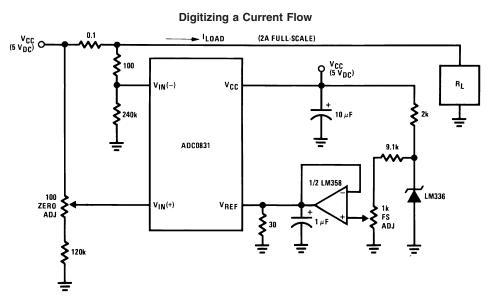
Digital Link and Sample Controlling Software for theSerially Oriented COP420 and the Bit Programmable I/O INS8048



Applications (Continued)				MPLE	
Cop Coding	Example		Mnemor		Instruction
Mnemonic LEI SC OGI CLR A AISC 1 XAS LDD NOP XAS	Instruction ENABLES SIO'S INPUT AND OUTPUT C = 1 G0=0 (CS =0) CLEARS ACCUMULATOR LOADS ACCUMULATOR WITH 1 EXCHANGES SIO WITH ACCUMULATOR AND STARTS SK CLOCK LOADS MUX ADDRESS FROM RAM INTO ACCUMULATOR — LOADS MUX ADDRESS FROM ACCUMULATOR TO SIO REGISTER ↑ 8 INSTRUCTIONS	START: LOOP 1: ZERO: ONE: CONT:	DJNZ	B, #5 A, #ADDR A ONE P1, #0FEH CONT P1, #1 PULSE B, LOOP 1 PULSE	;CY←ADDRESS BIT ;TEST BIT ;BIT=0 ;DI←0 ;CONTINUE ;BIT=1 ;DI←1 ;PULSE SK 0→1→0
XAS XIS CLR A RC XAS XIS OGI LEI	↓ READS HIGH ORDER NIBBLE (4 BITS) INTO ACCUMULATOR PUTS HIGH ORDER NIBBLE INTO RAM CLEARS ACCUMULATOR C = 0 READS LOW ORDER NIBBLE INTO ACCUMULATOR AND STOPS SK PUTS LOW ORDER NIBBLE INTO RAM $G0=1$ ( $\overline{CS}=1$ ) DISABLES SIO'S INPUT AND OUTPUT	LOOP 2: RETR PULSE:	IN RRC MOV RLC MOV	PULSE A, P1 A A A, C A C, A	;PULSE SK $0 \rightarrow 1 \rightarrow 0$ ;CY $\leftarrow$ DO ;A $\leftarrow$ RESULT ;A(0) $\leftarrow$ BIT AND SHIF ;C $\leftarrow$ RESULT ;CONTINUE UNTIL DONE ;PULSE SUBROUTIN ;SK $\leftarrow 1$ ;DELAY

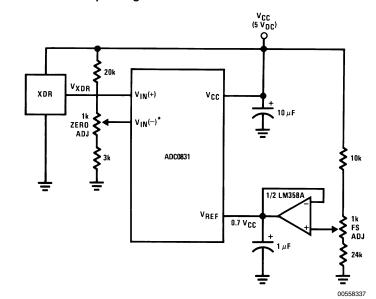


# Applications (Continued)

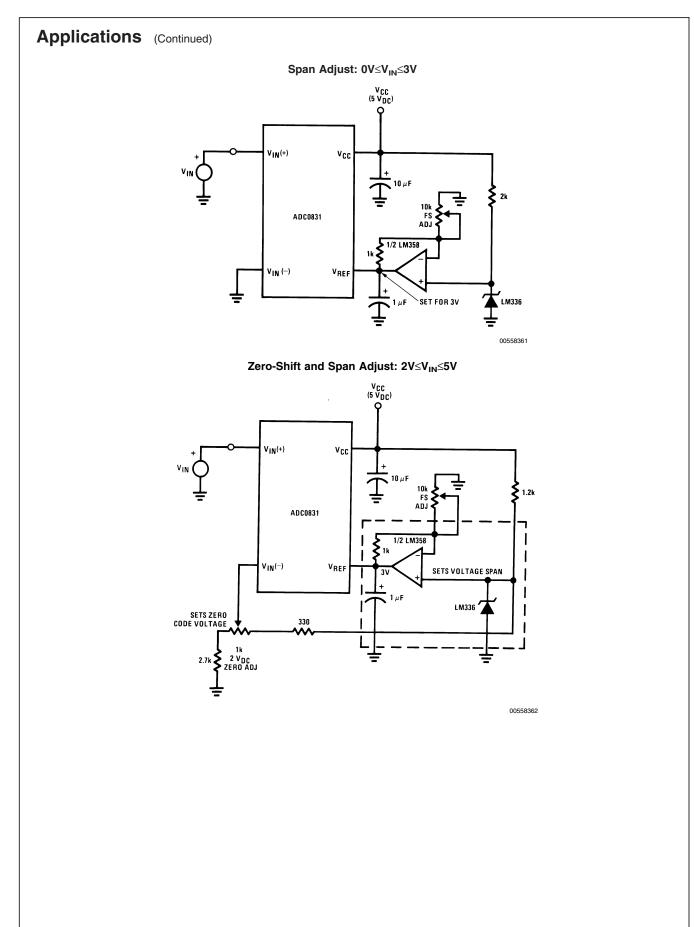


00558315

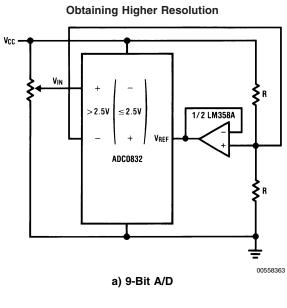
**Operating with Ratiometric Transducers** 

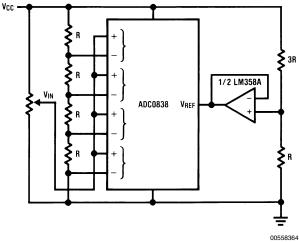


 $^{*}V_{IN}(-)$  = 0.15  $V_{CC}$  15% of  $V_{CC} \leq V_{XDR} \leq 85\%$  of  $V_{CC}$ 



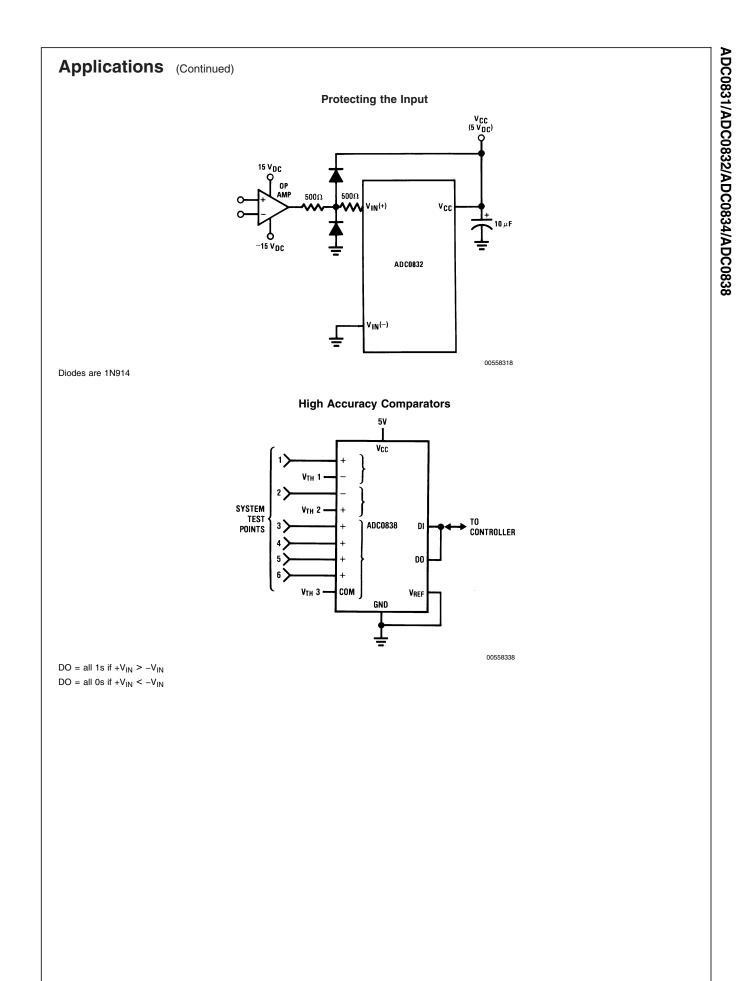
# Applications (Continued)



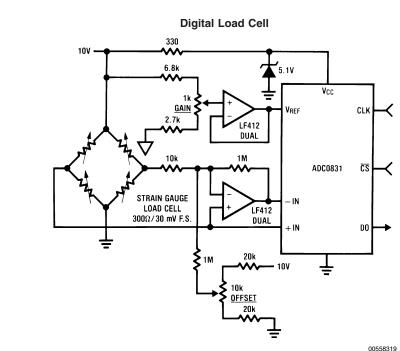


Controller performs a routine to determine which input polarity (9-bit example) or which channel pair (10-bit example) provides a non-zero output code. This information provides the extra bits.

b) 10-Bit A/D



# Applications (Continued)



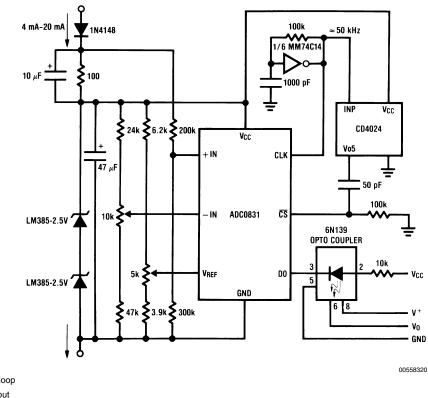
•Uses one more wire than load cell itself

•Two mini-DIPs could be mounted inside load cell for digital output transducer

•Electronic offset and gain trims relax mechanical specs for gauge factor and offset

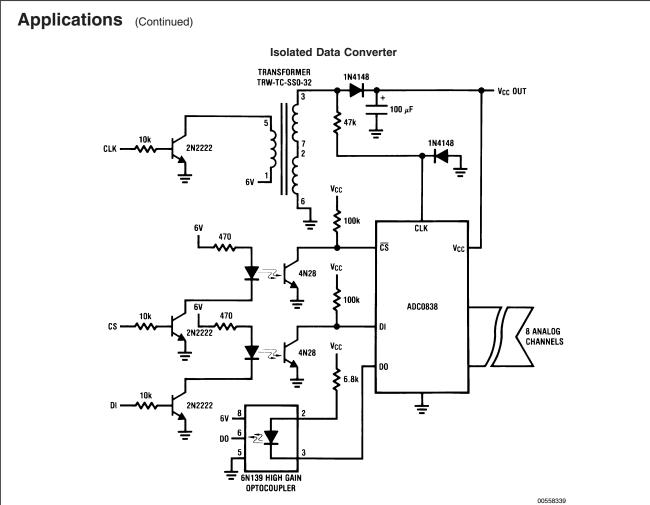
•Low level cell output is converted immediately for high noise immunity

#### 4 mA-20 mA Current Loop Converter



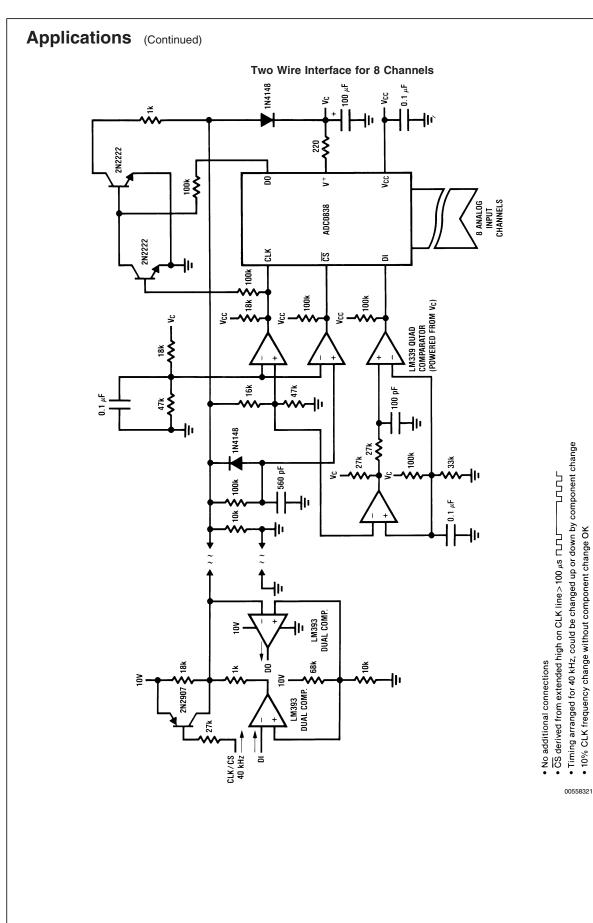
•All power supplied by loop

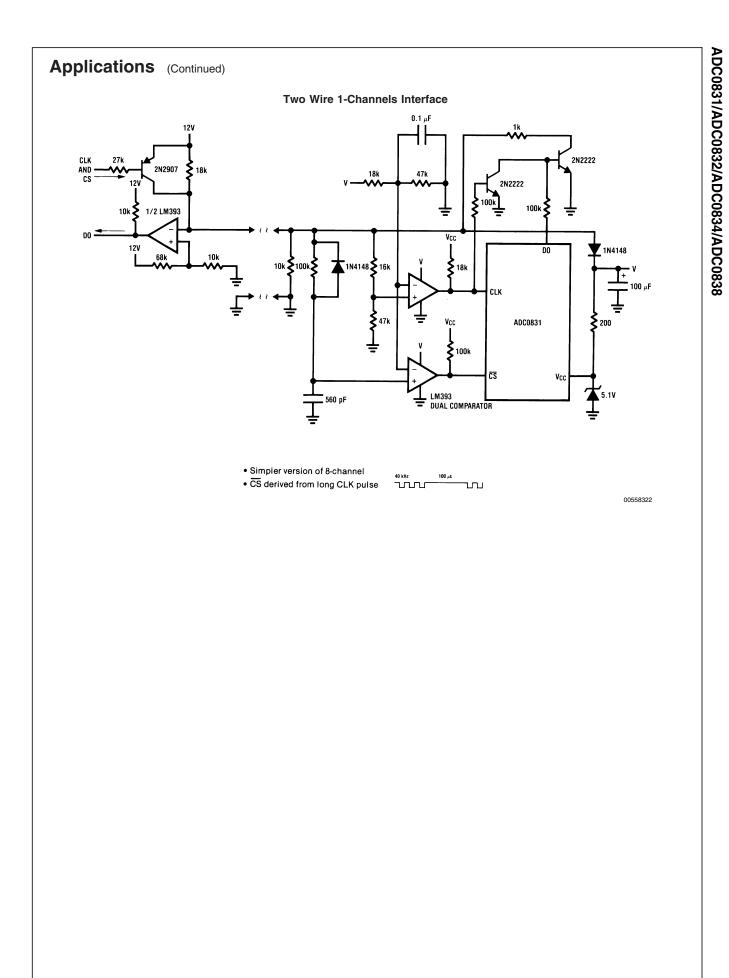
•1500V isolation at output

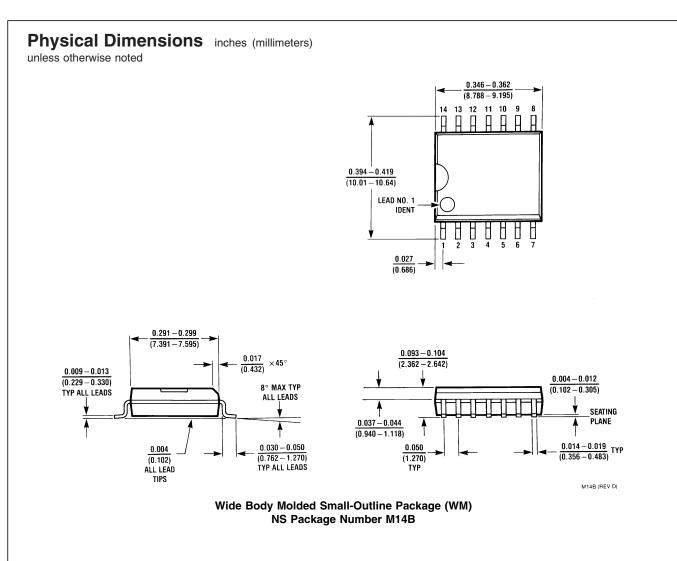


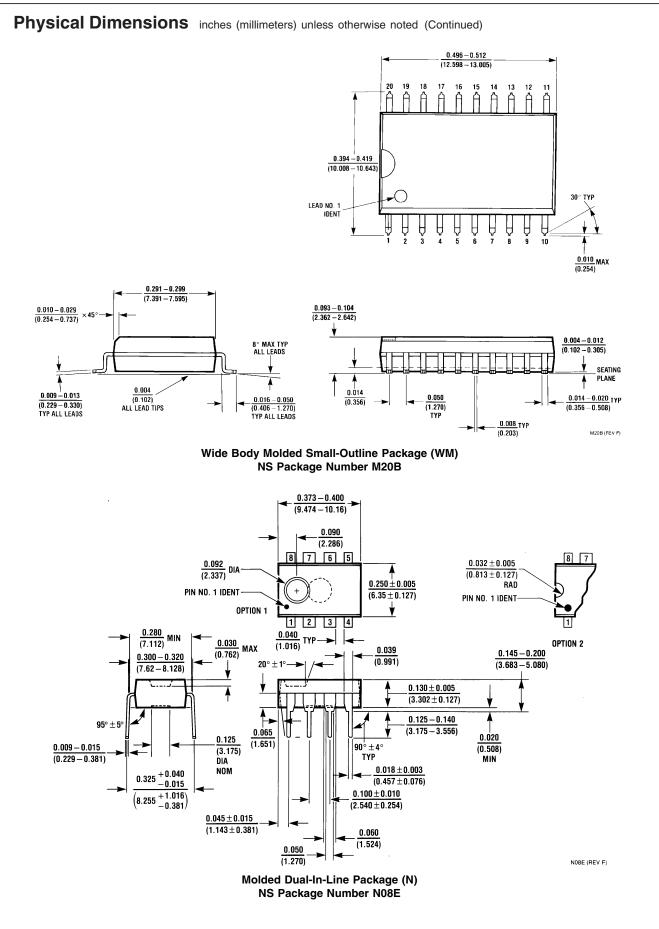
No power required remotely
1500V isolation

# ADC0831/ADC0832/ADC0834/ADC0838





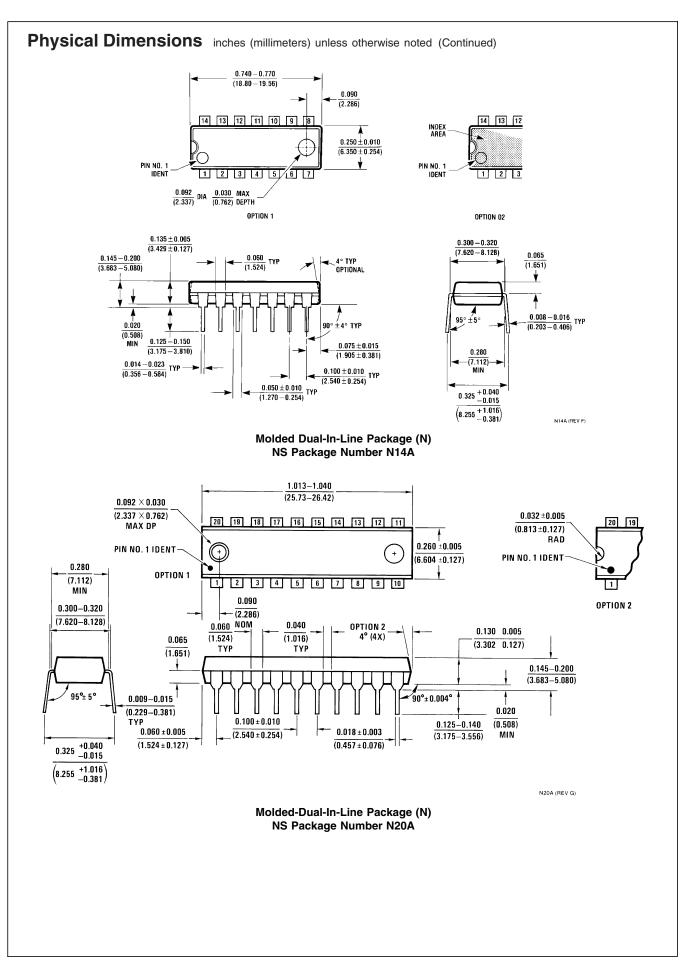


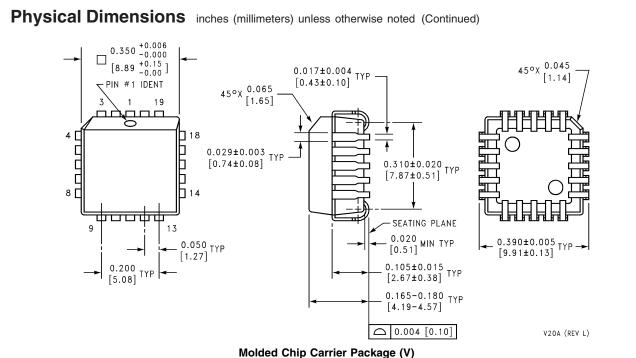


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ADC0831/ADC0832/ADC0834/ADC0838







Molded Chip Carrier Package (V) Order Number ADC0838BCV or ADC0838CCV NS Package Number V20A

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